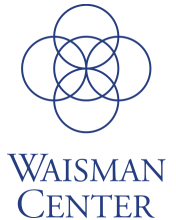


# A hierarchical task-based control model of speech incorporating sensory feedback

Ben Parrell\*

*University of Wisconsin  
Communication Sciences & Disorders*



Vikram Ramanarayanan\*

*Educational Testing Service  
University of California, San Francisco*



Sri Nagarajan, John Houde

*University of California, San Francisco*

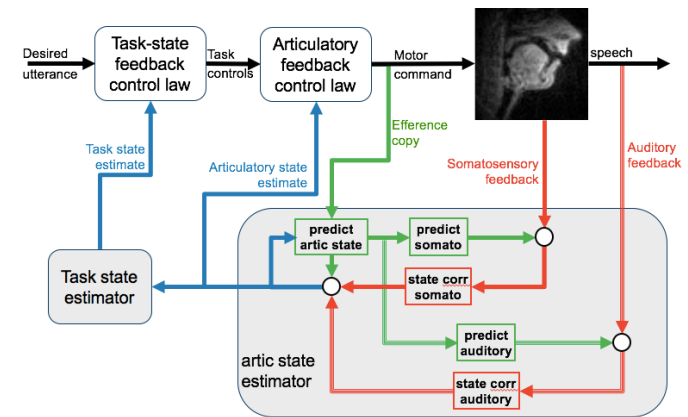
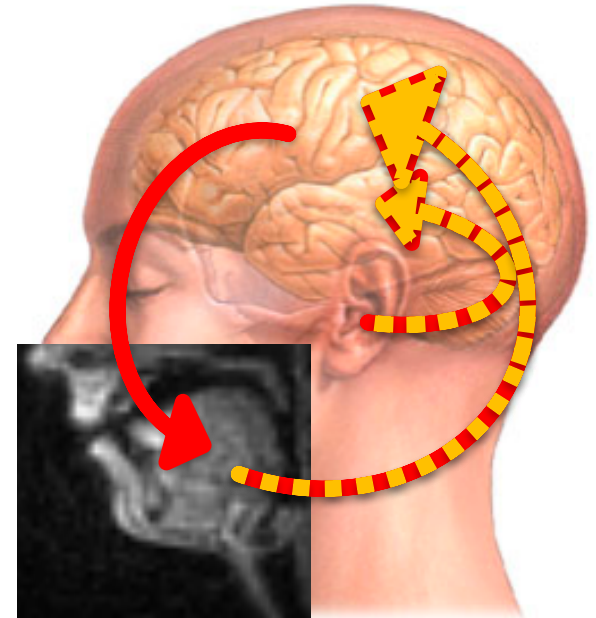


University of California  
San Francisco

*\*equal contribution*

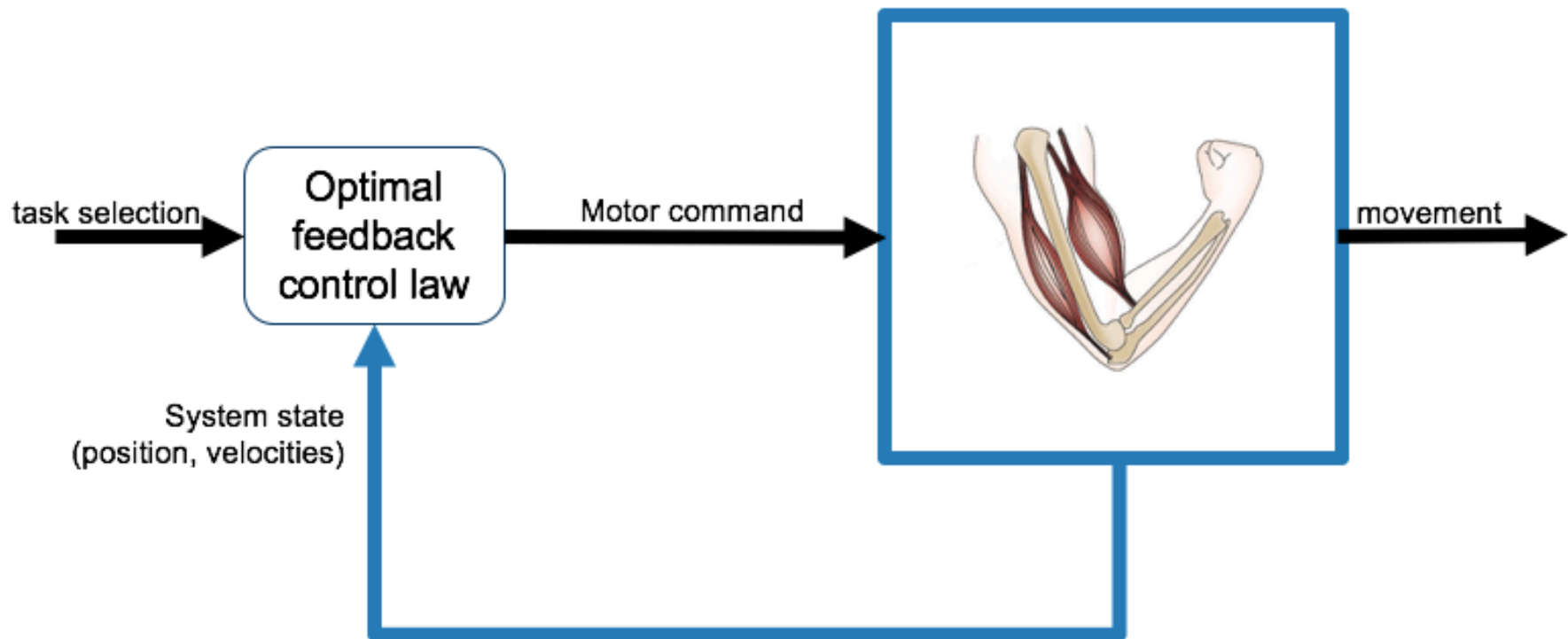
# The sensory system in speech production

- Speech is responsive to sensory feedback
  - Delayed auditory feedback disrupts fluent speech  
(Lee, 1950; Yates, 1963)
  - Speakers compensate for all manner of auditory and somatosensory feedback perturbations  
(e.g. Houde 1998; Burnett 1998; Tremblay 2003;...)
- But speech is not dependent on sensory feedback
  - Post-lingually deafened adults can be intelligible for decades  
(Waldstein, 1990; Cowie and Douglas-Cowie, 1992)
  - Speech is highly intelligible during oral sensory and auditory deprivation (though articulatory precision is affected)  
(Scott and Ringel, 1971; Ringel and Steer, 1963)

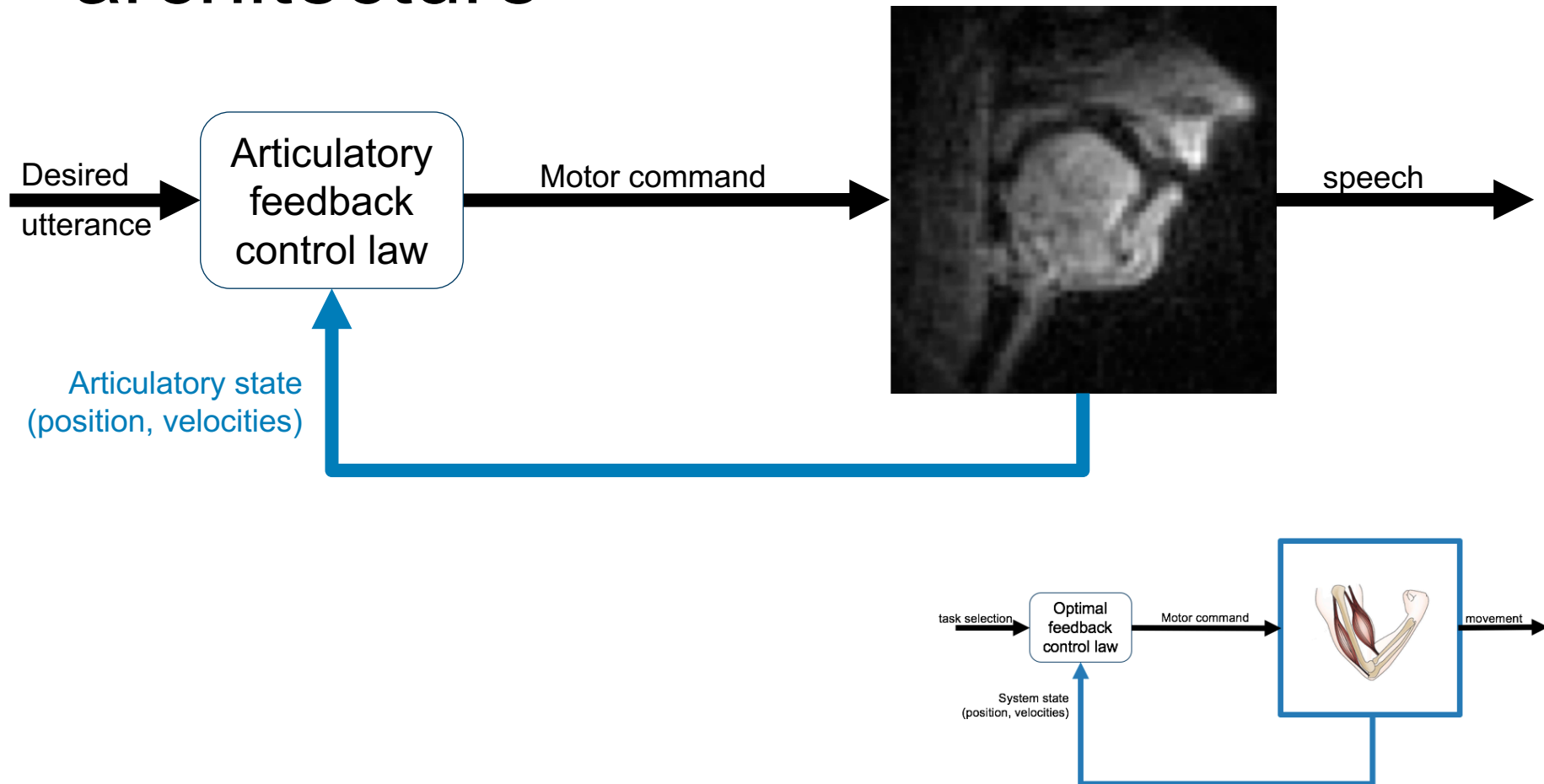


Feedback-Aware Control of Tasks in Speech (FACTS)

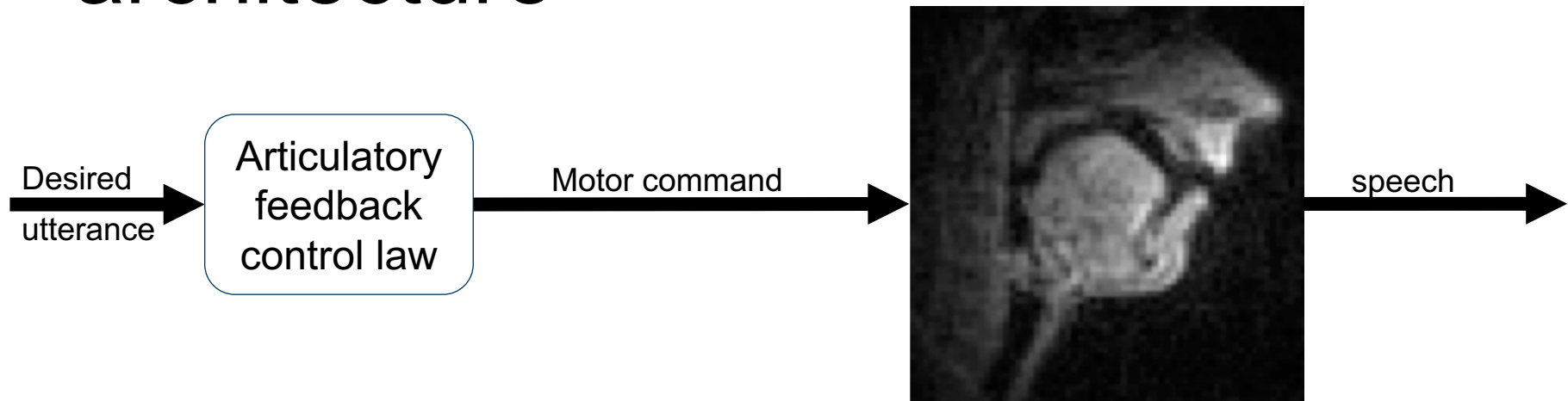
# FACTS is based on a domain-general State Feedback Control architecture



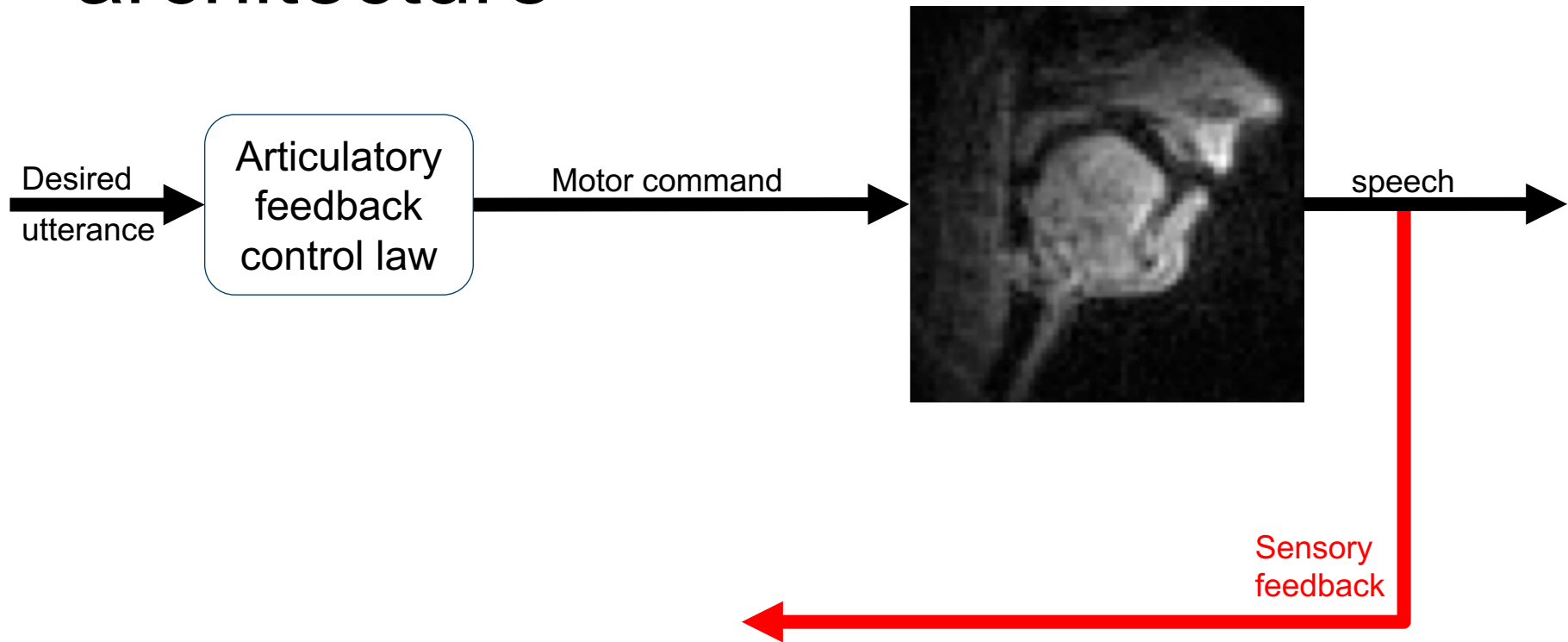
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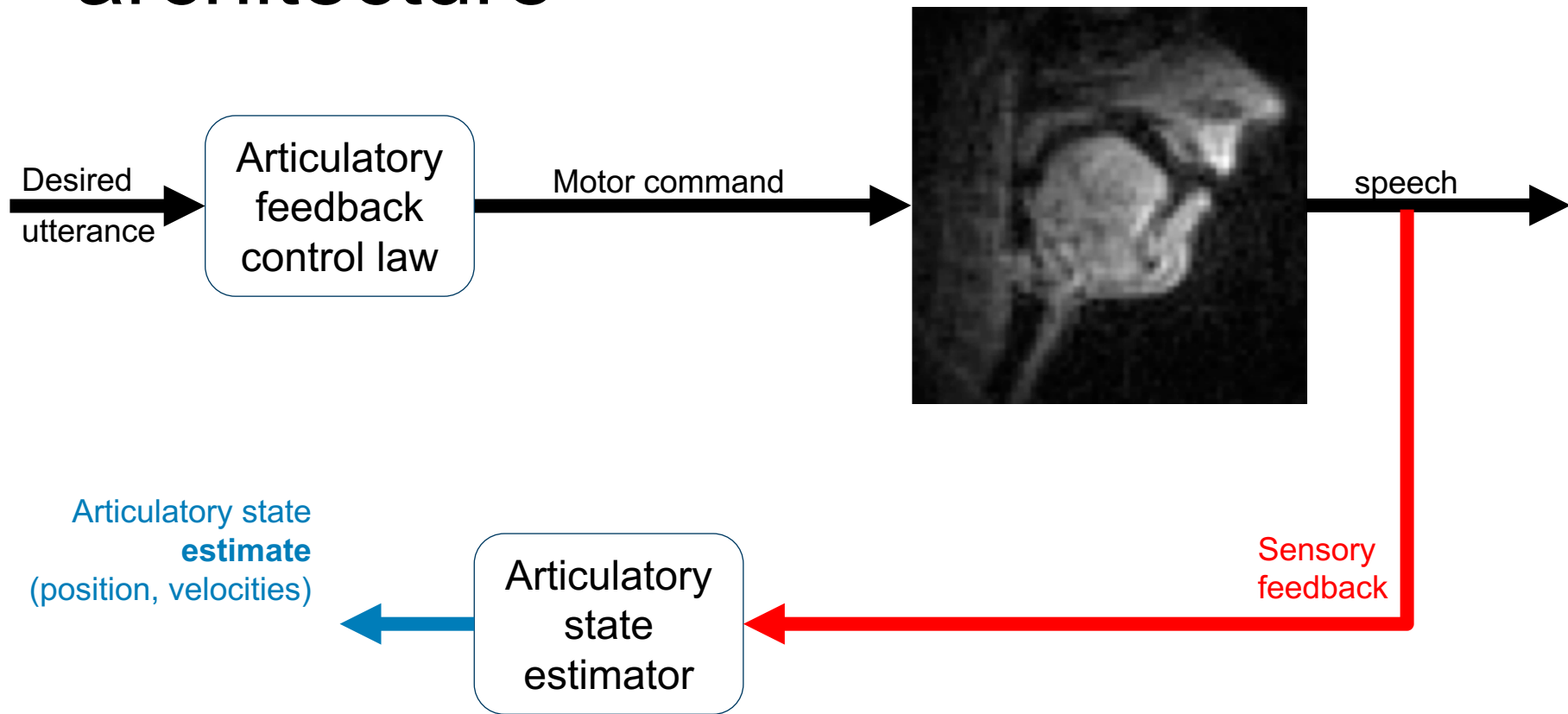
# FACTS is based on a domain-general State Feedback Control architecture



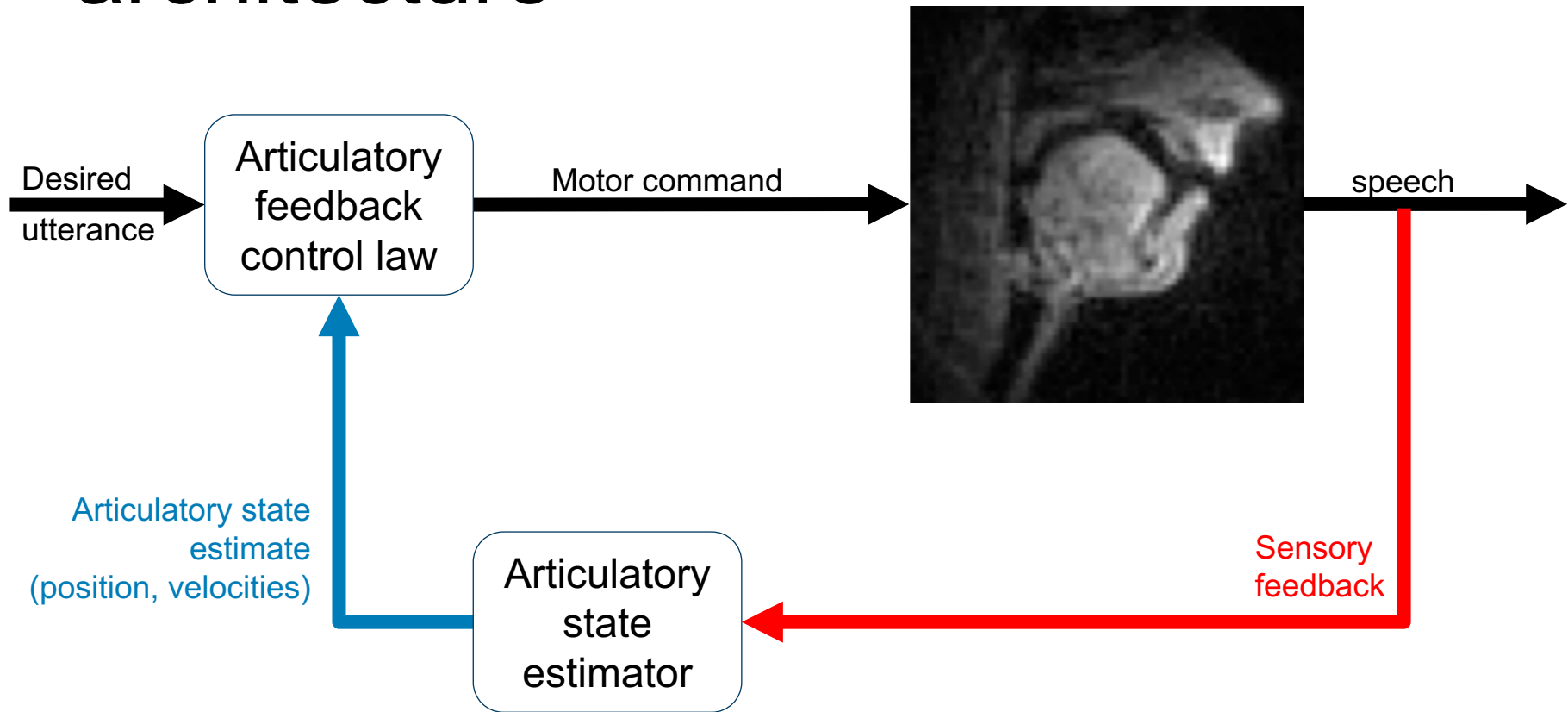
# FACTS is based on a domain-general State Feedback Control architecture



# FACTS is based on a domain-general State Feedback Control architecture

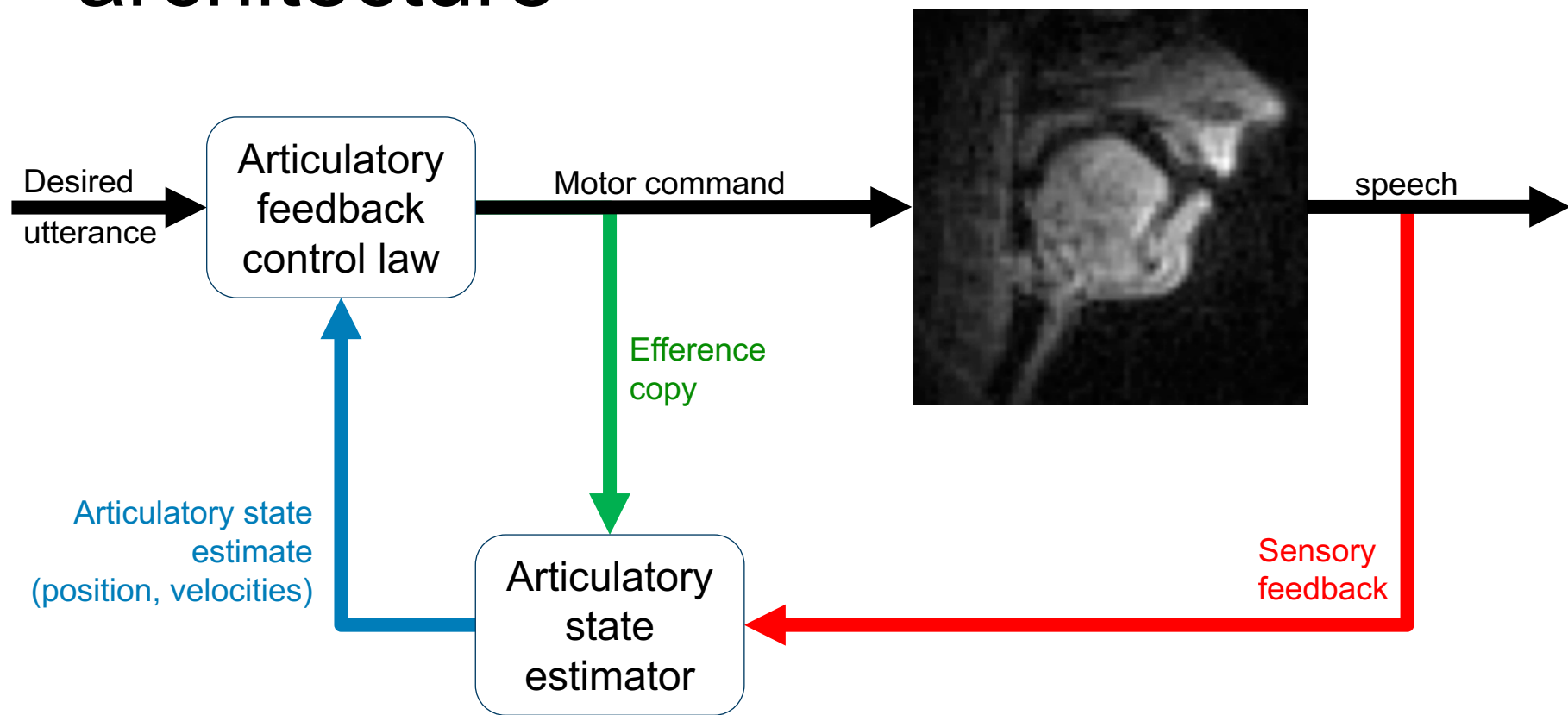


# FACTS is based on a domain-general State Feedback Control architecture

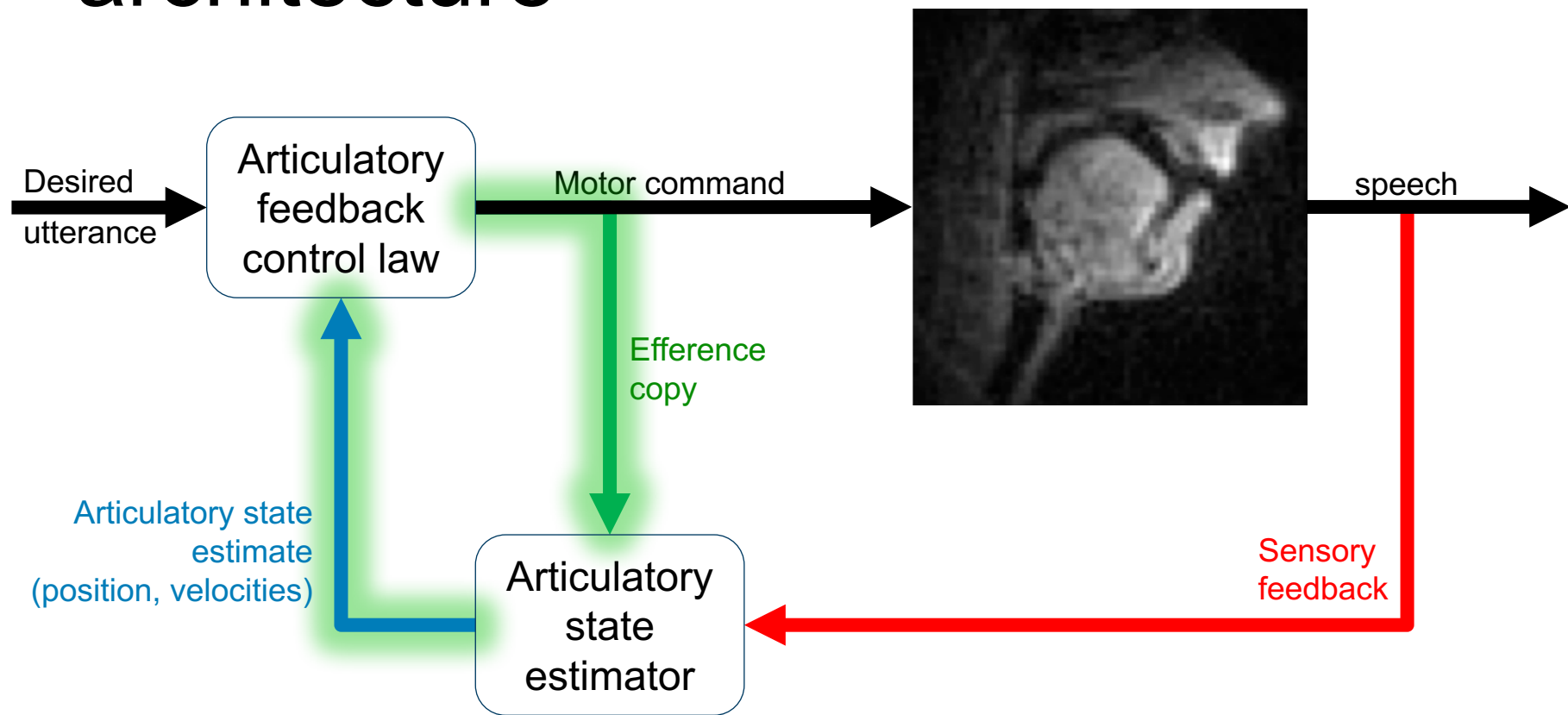




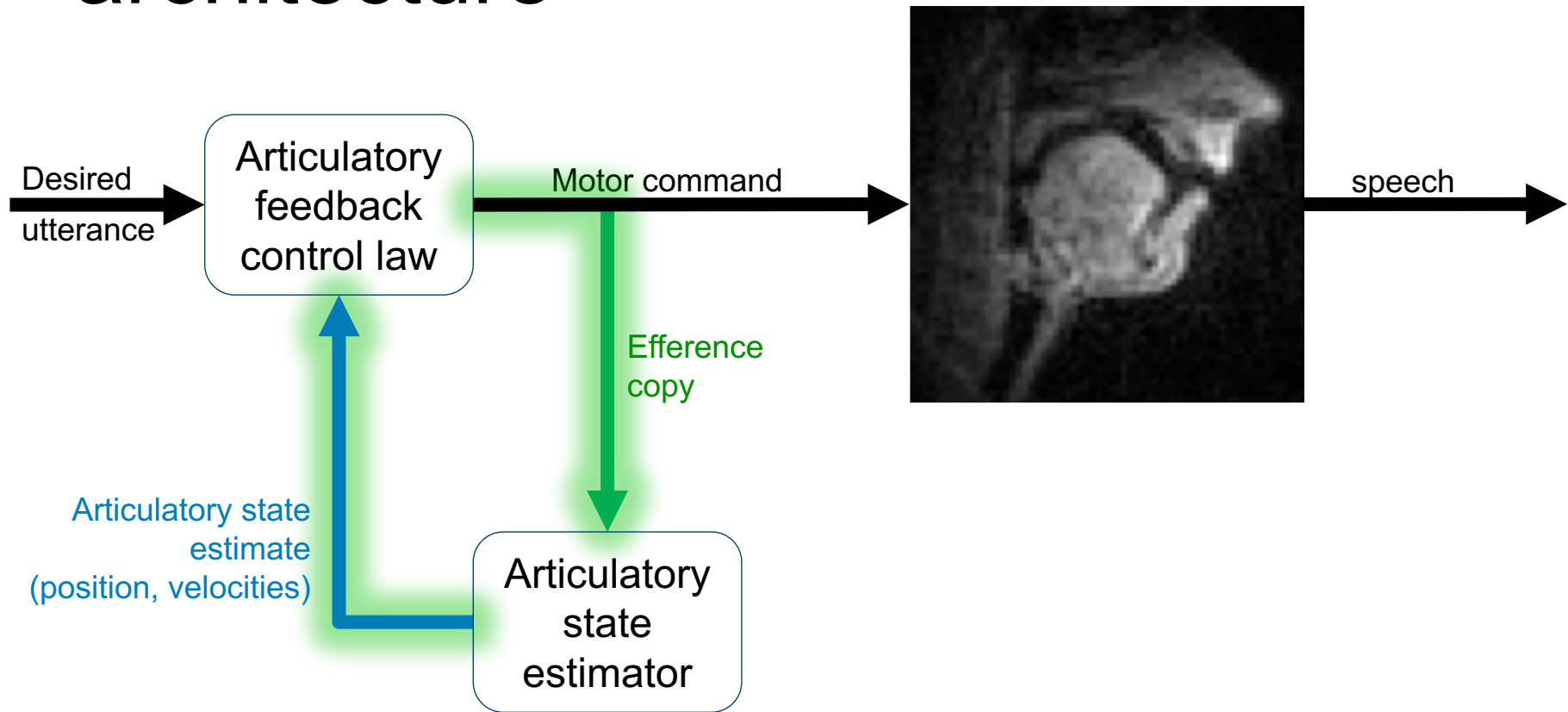
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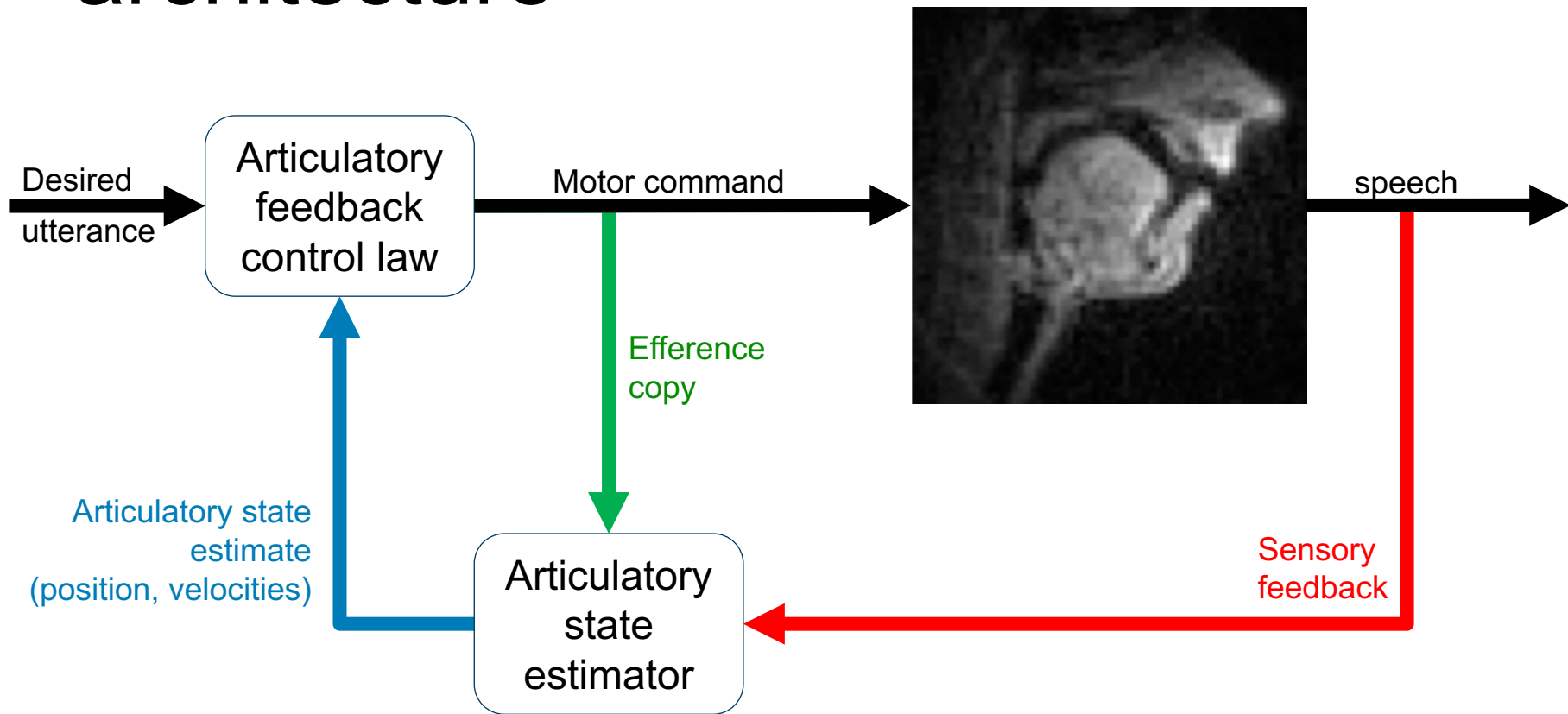
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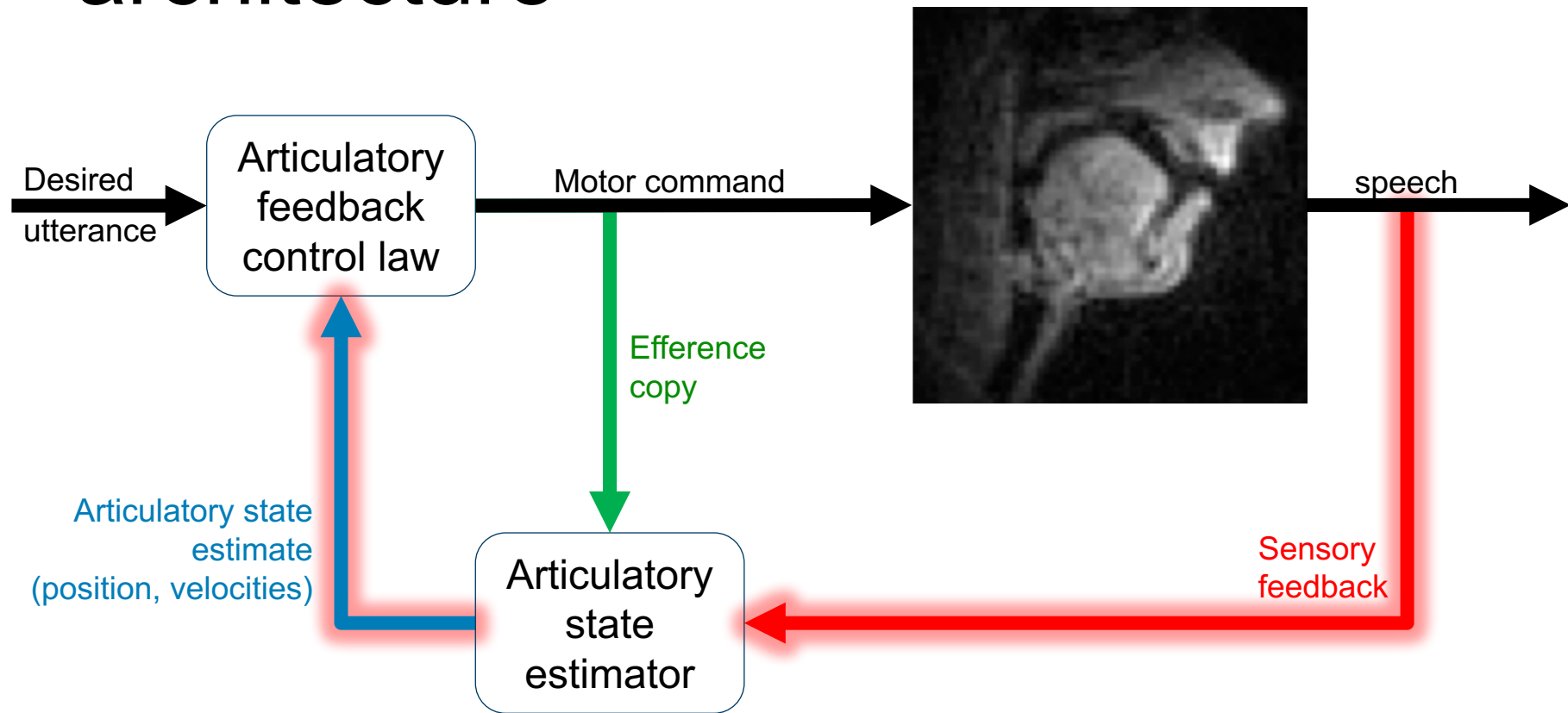
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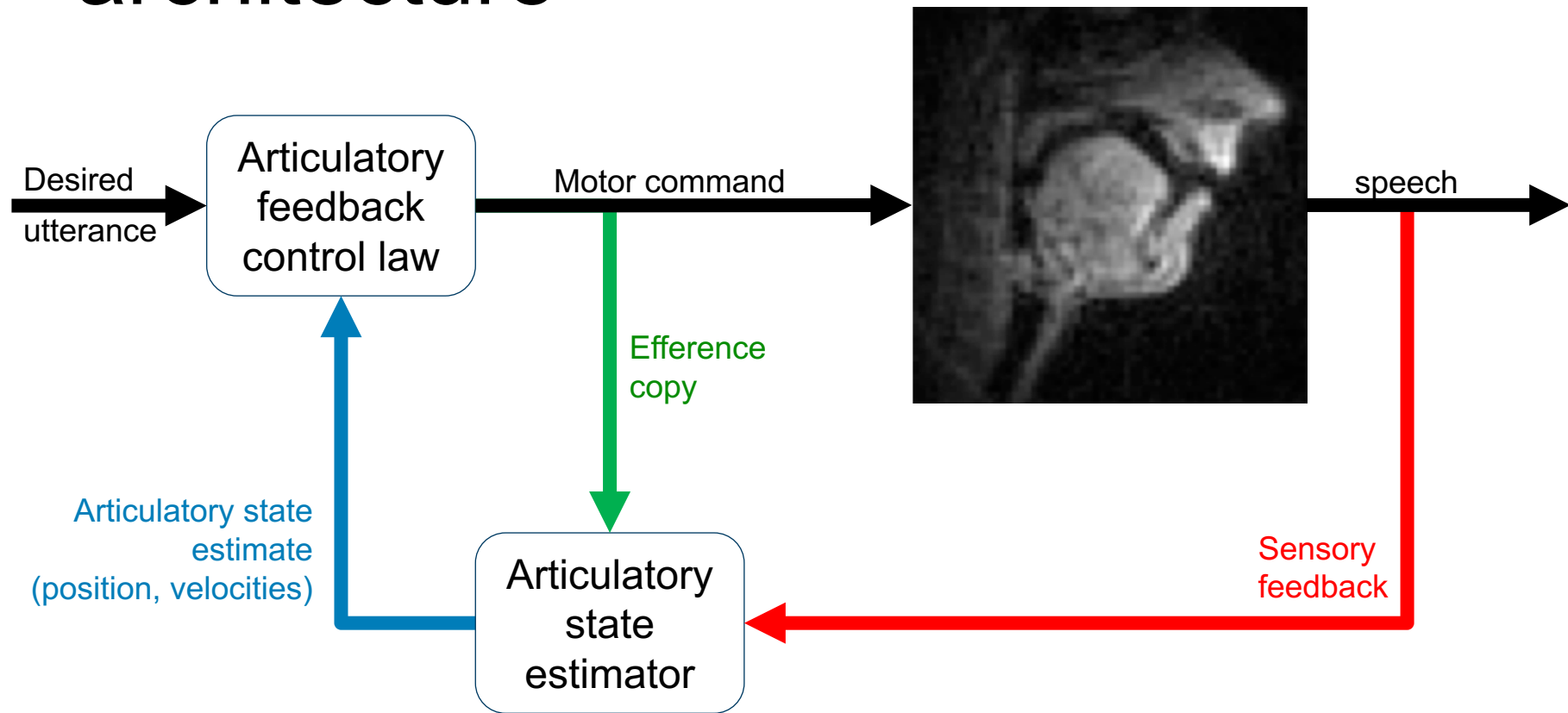
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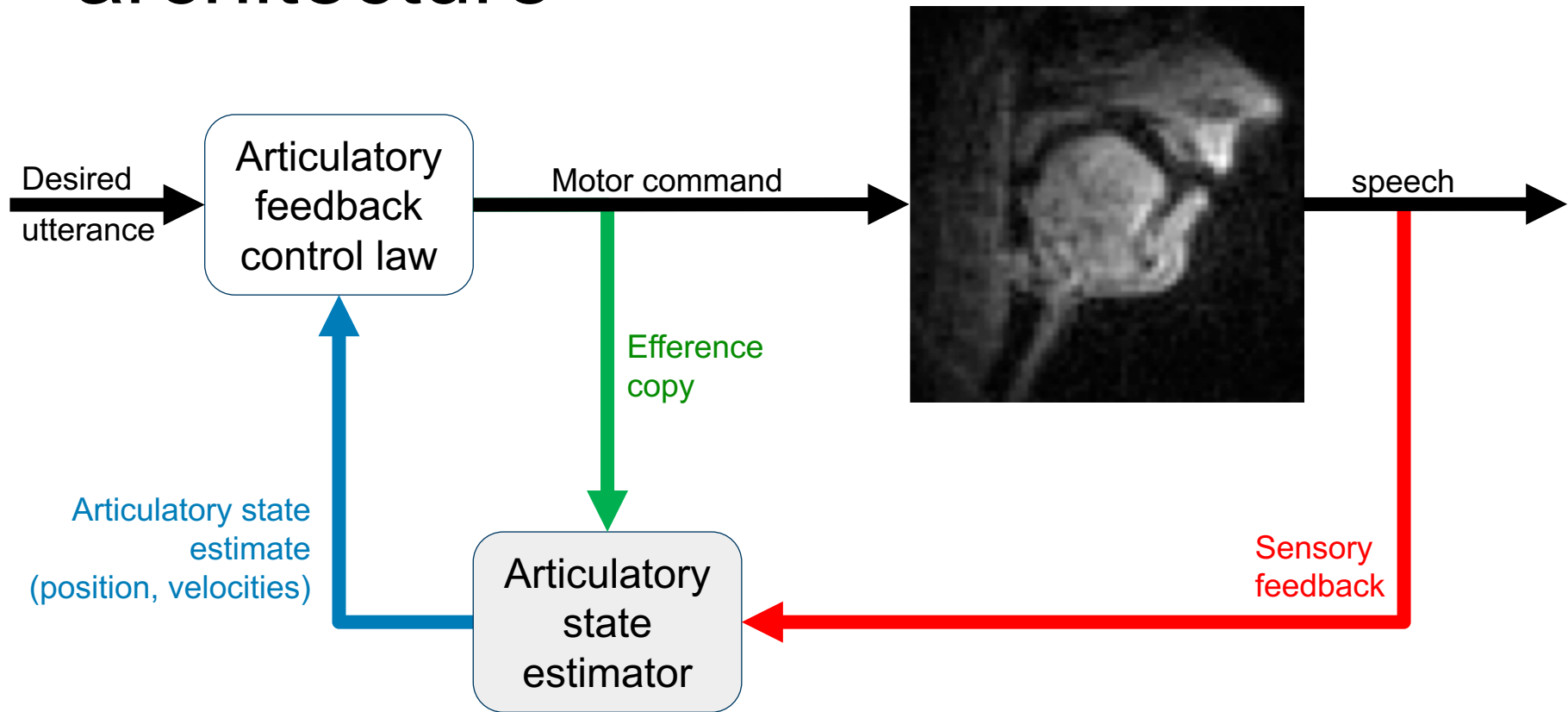
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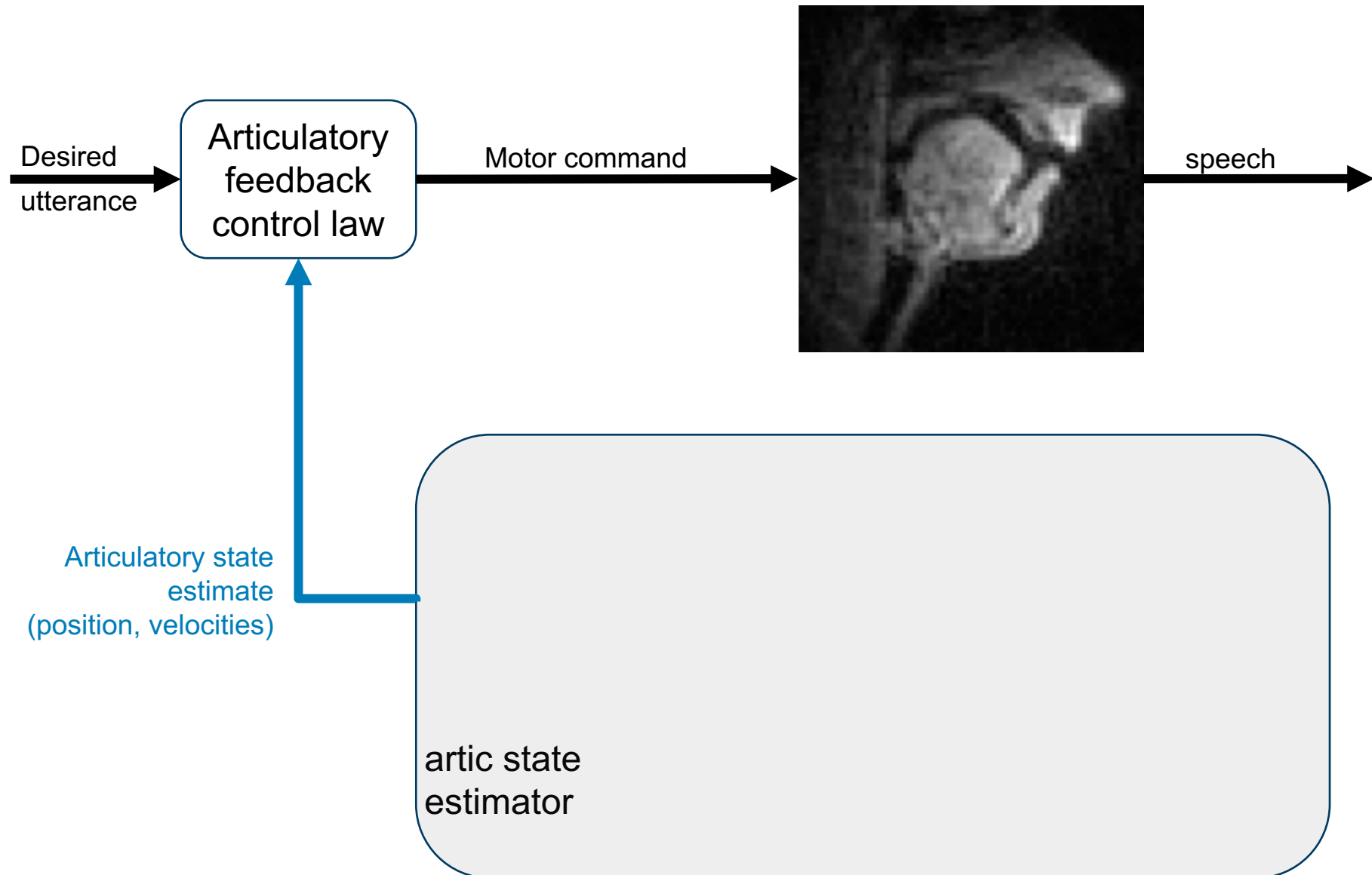
# FACTS is based on a domain-general State Feedback Control architecture



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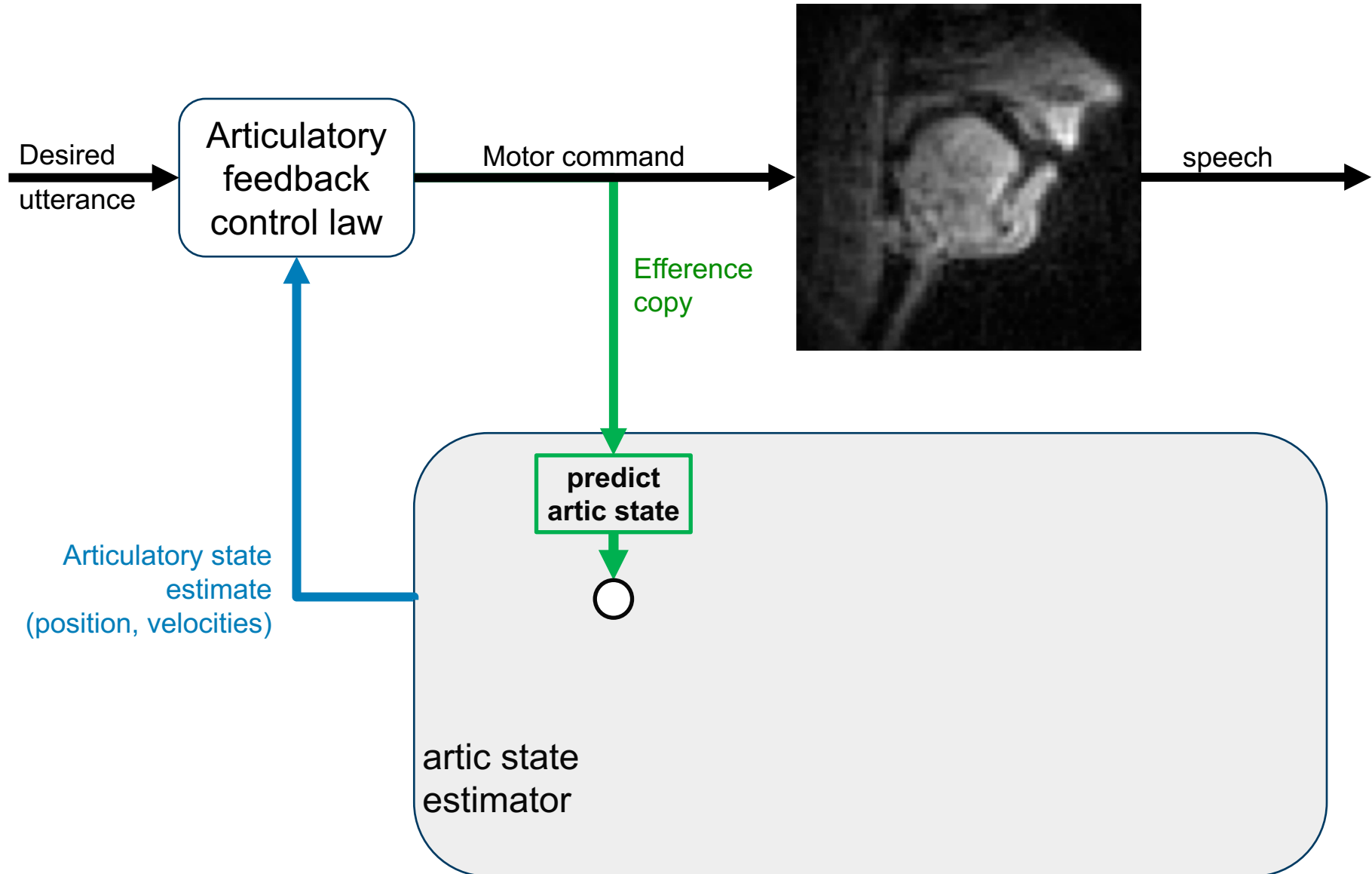


# Estimation of the articulatory state

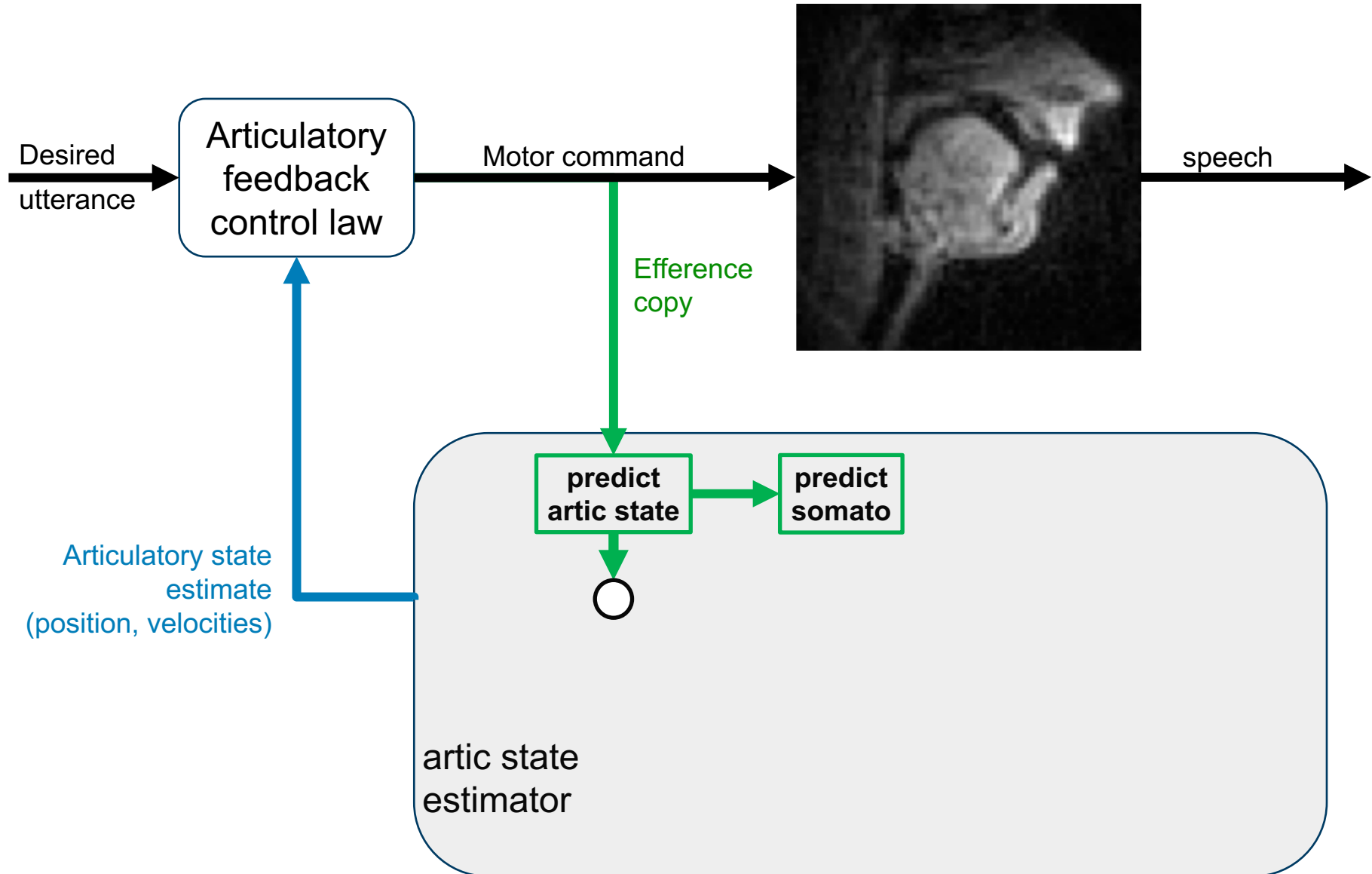




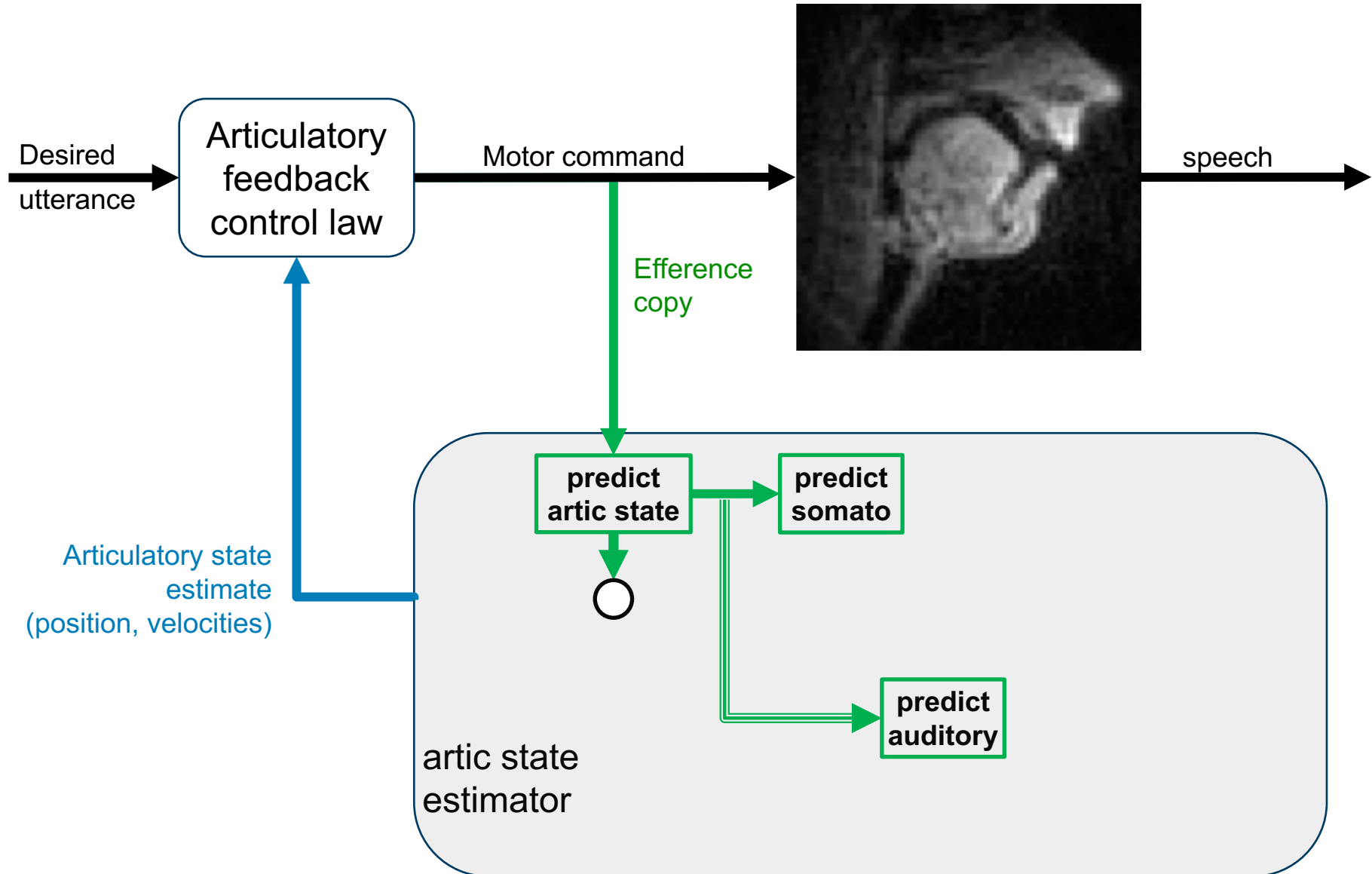
# Estimation of the articulatory state



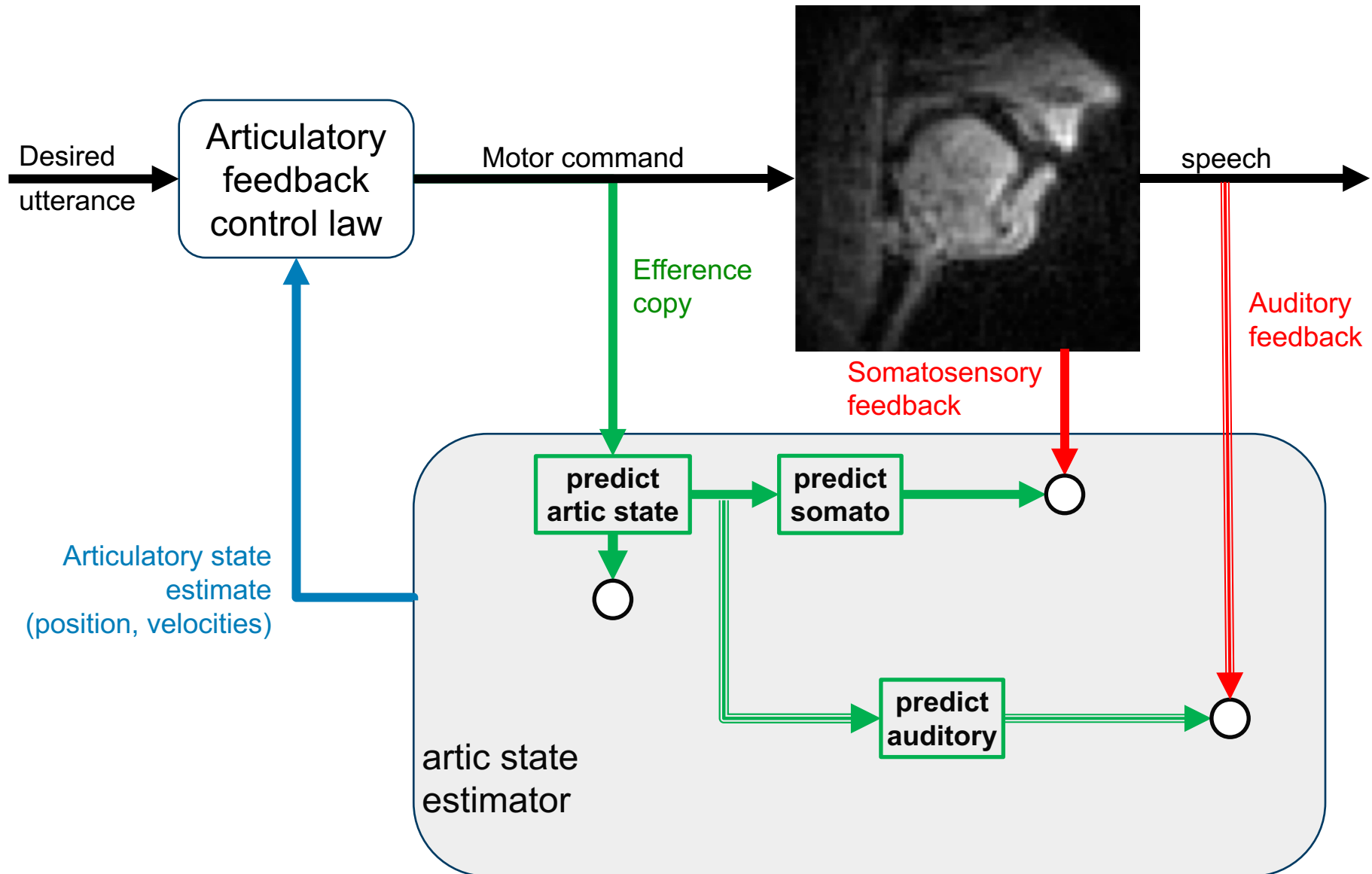
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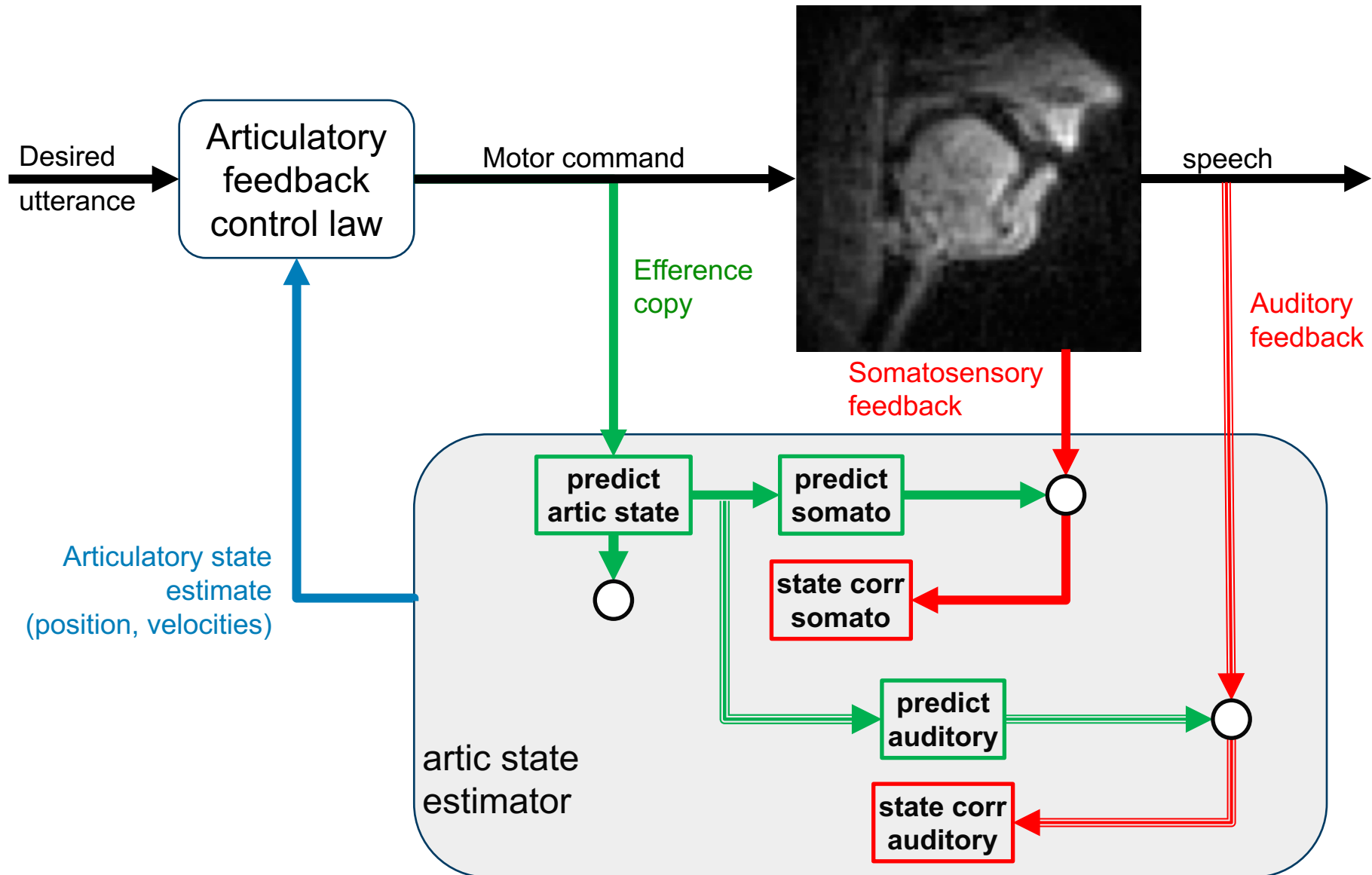
# Estimation of the articulatory state



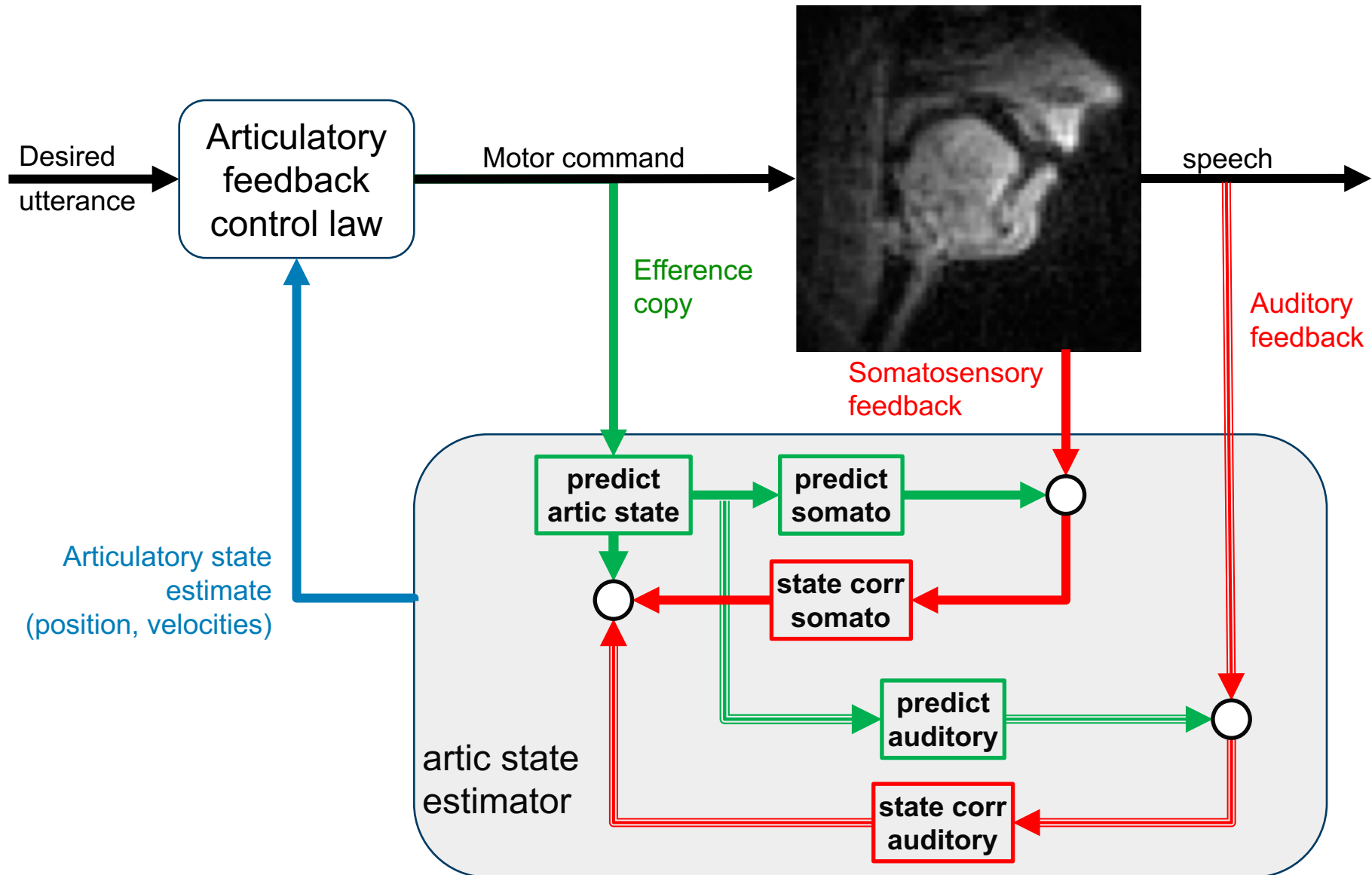
# Estimation of the articulatory state



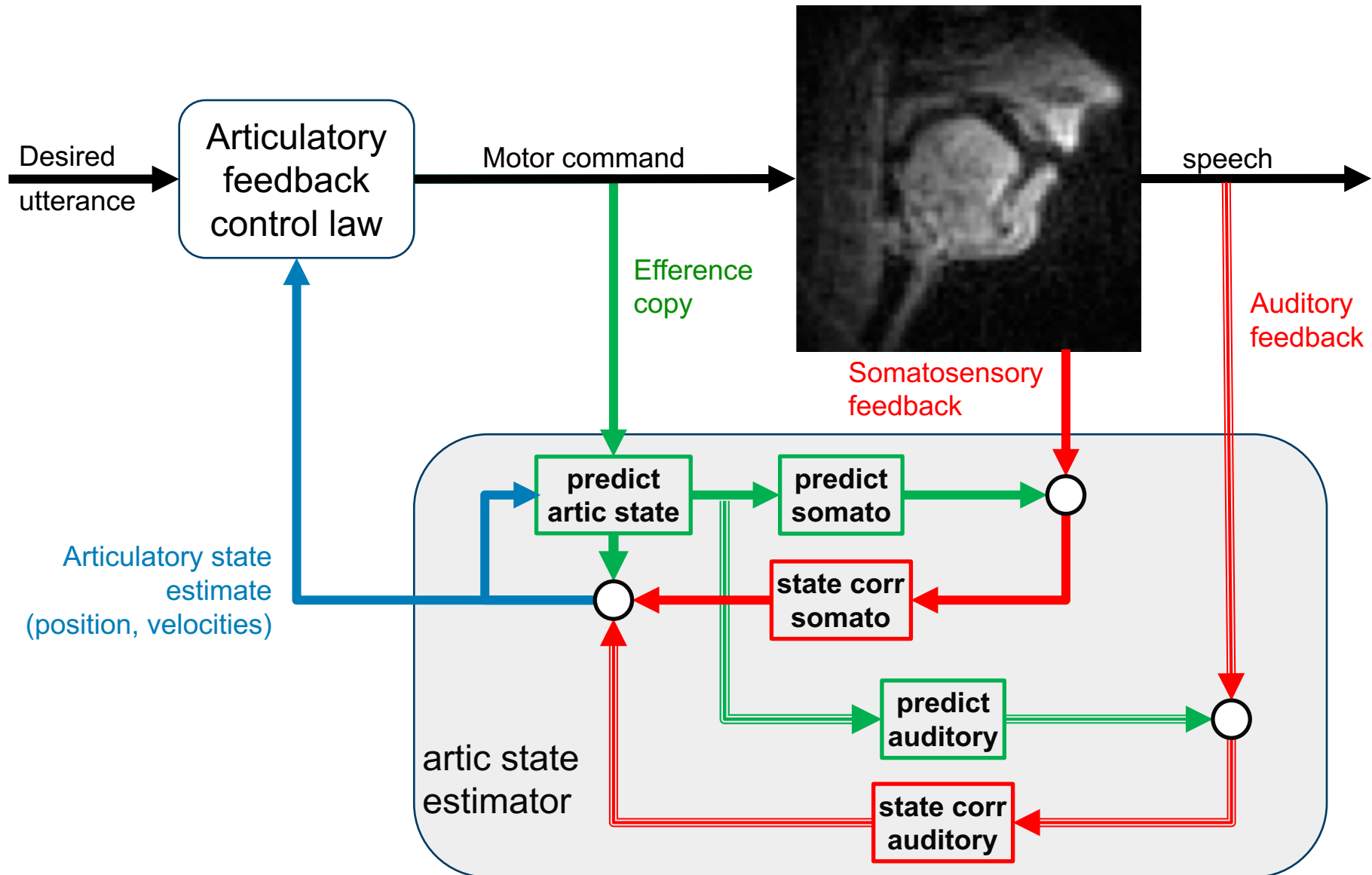
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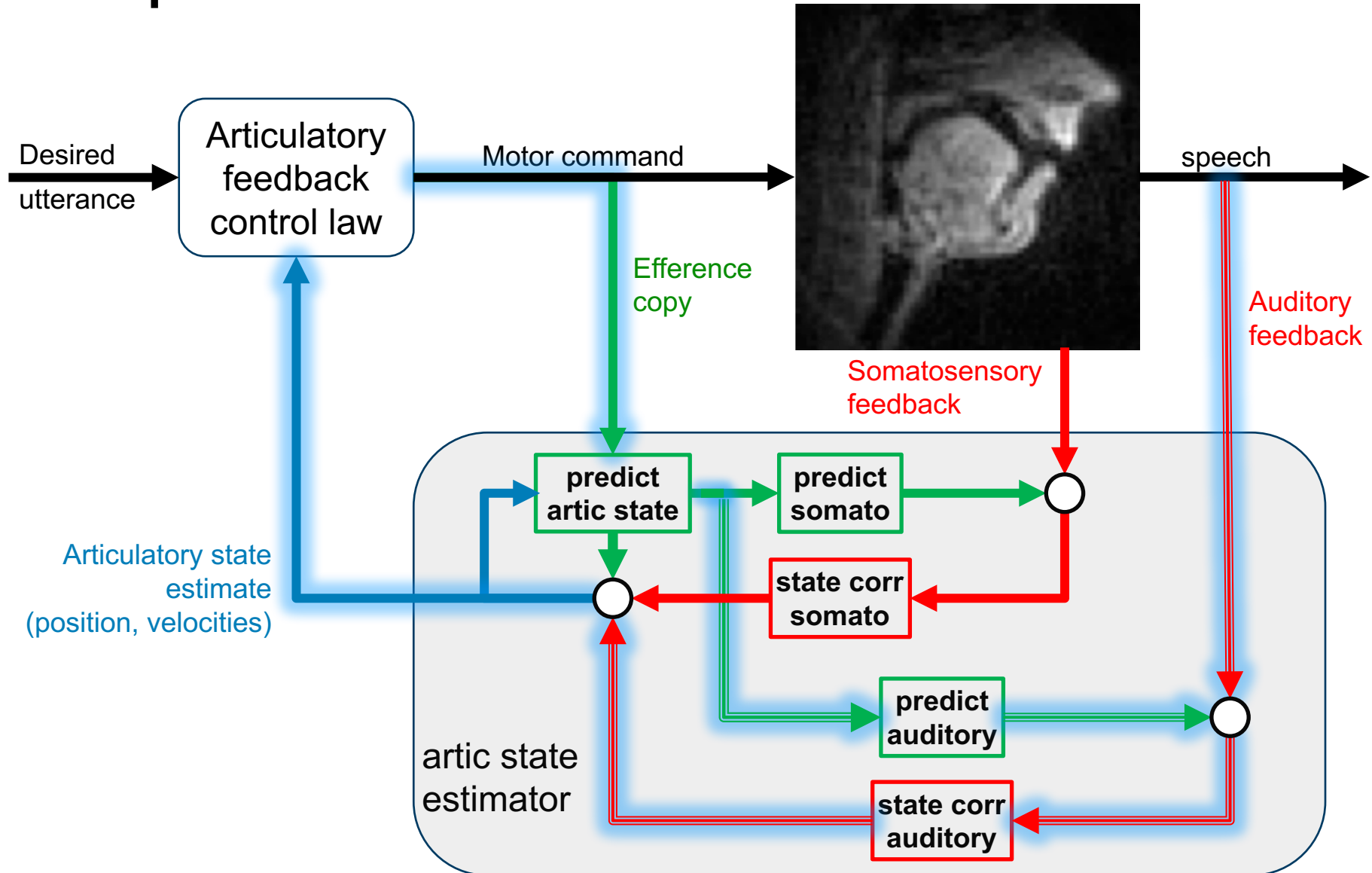
# Estimation of the articulatory state



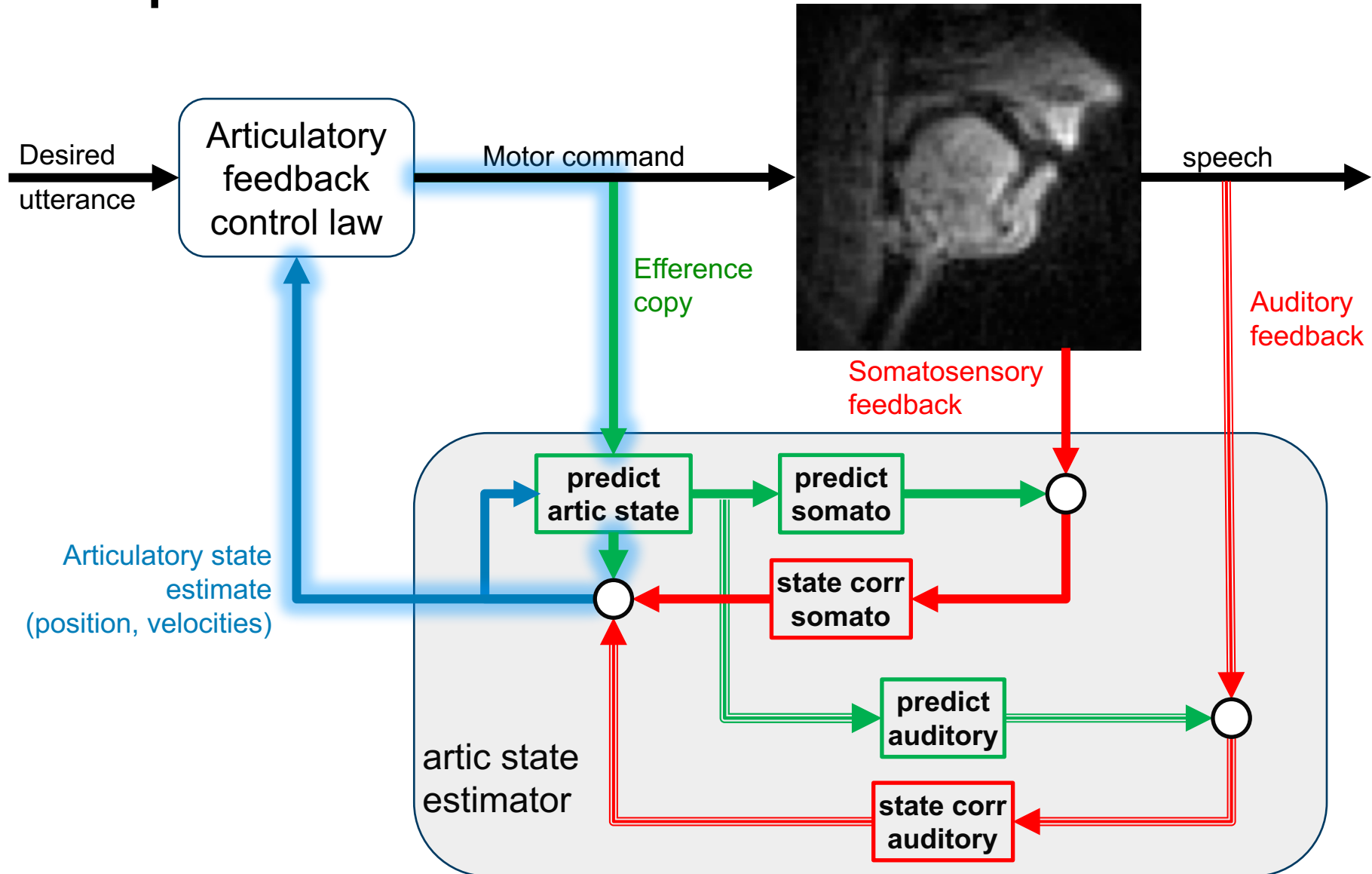




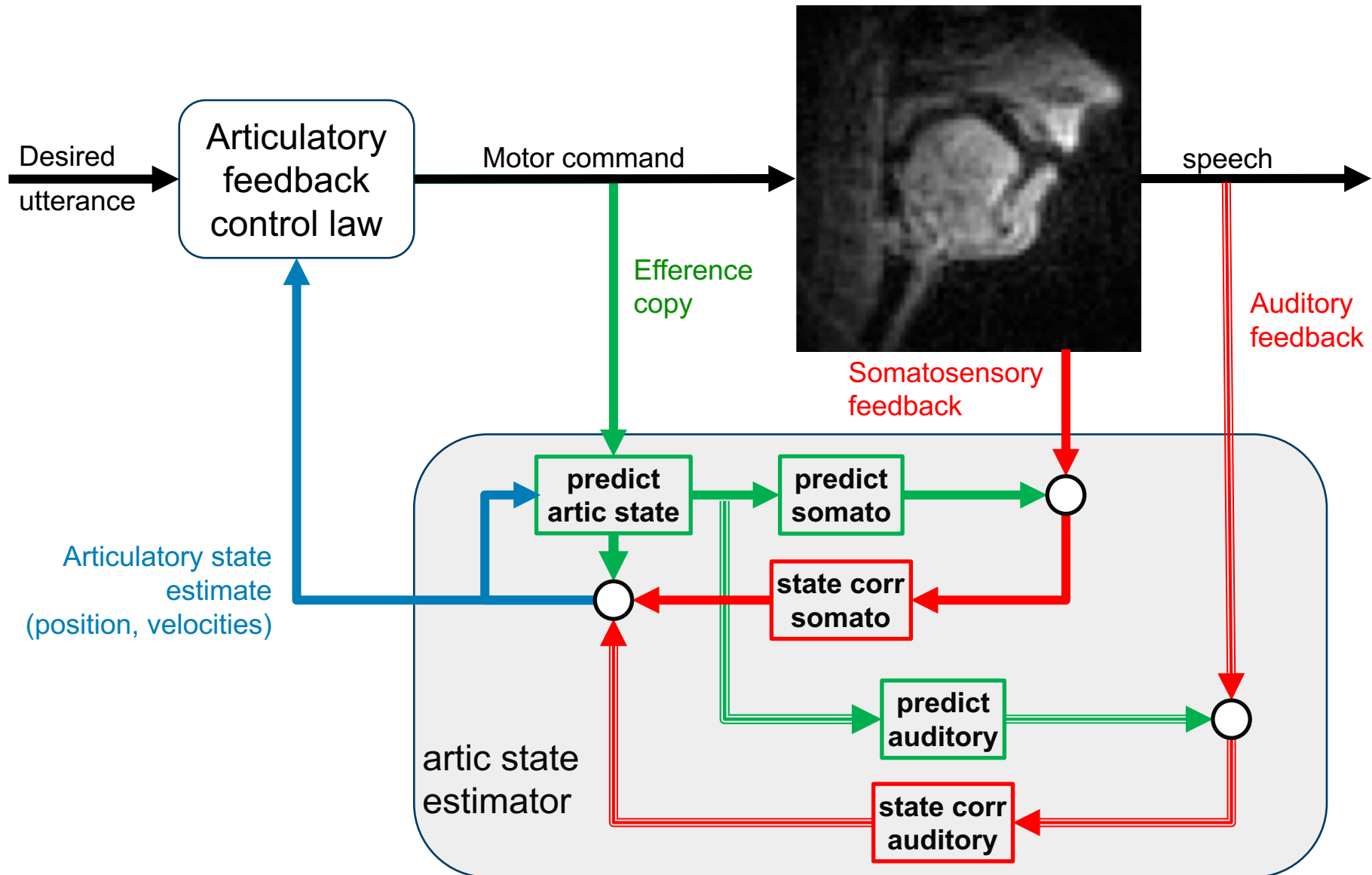
# FACTS has an auditory feedback loop



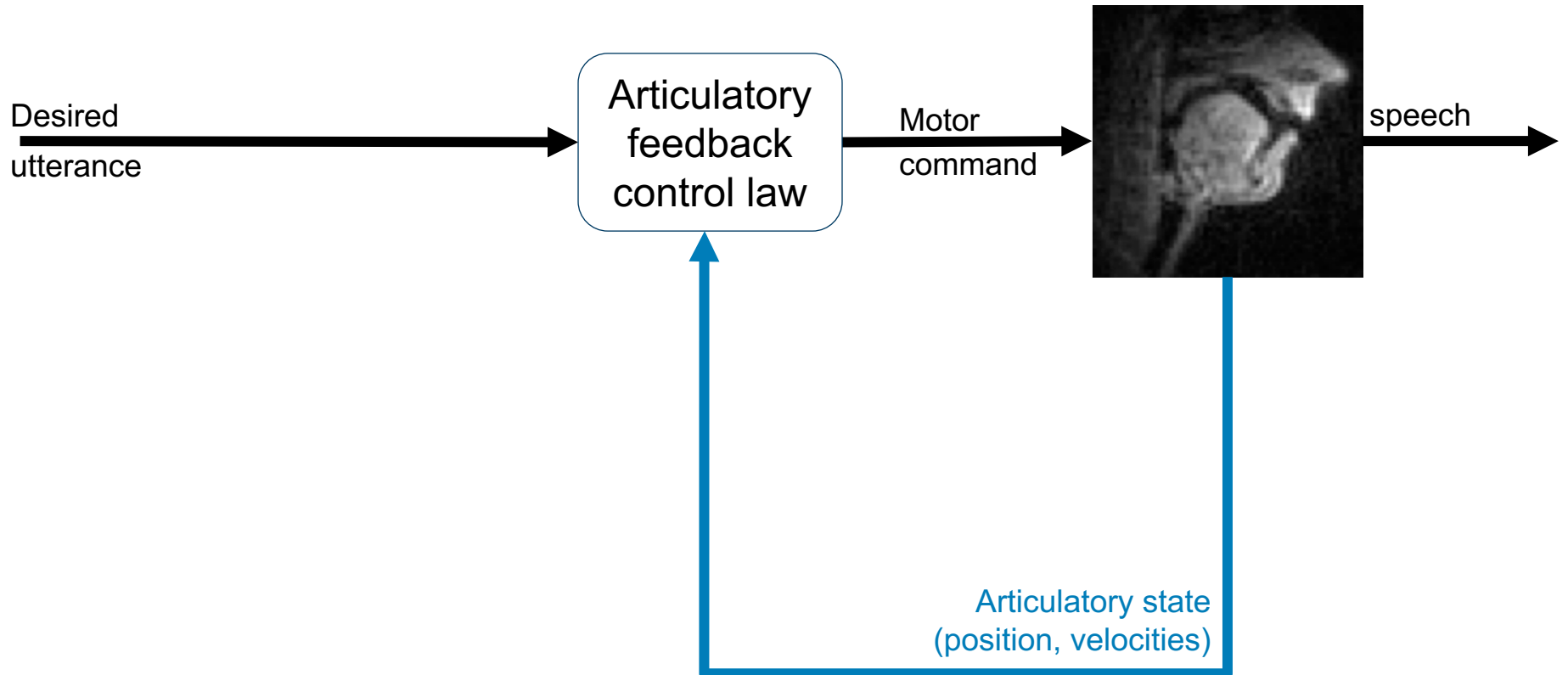
# FACTS has a predictive control loop



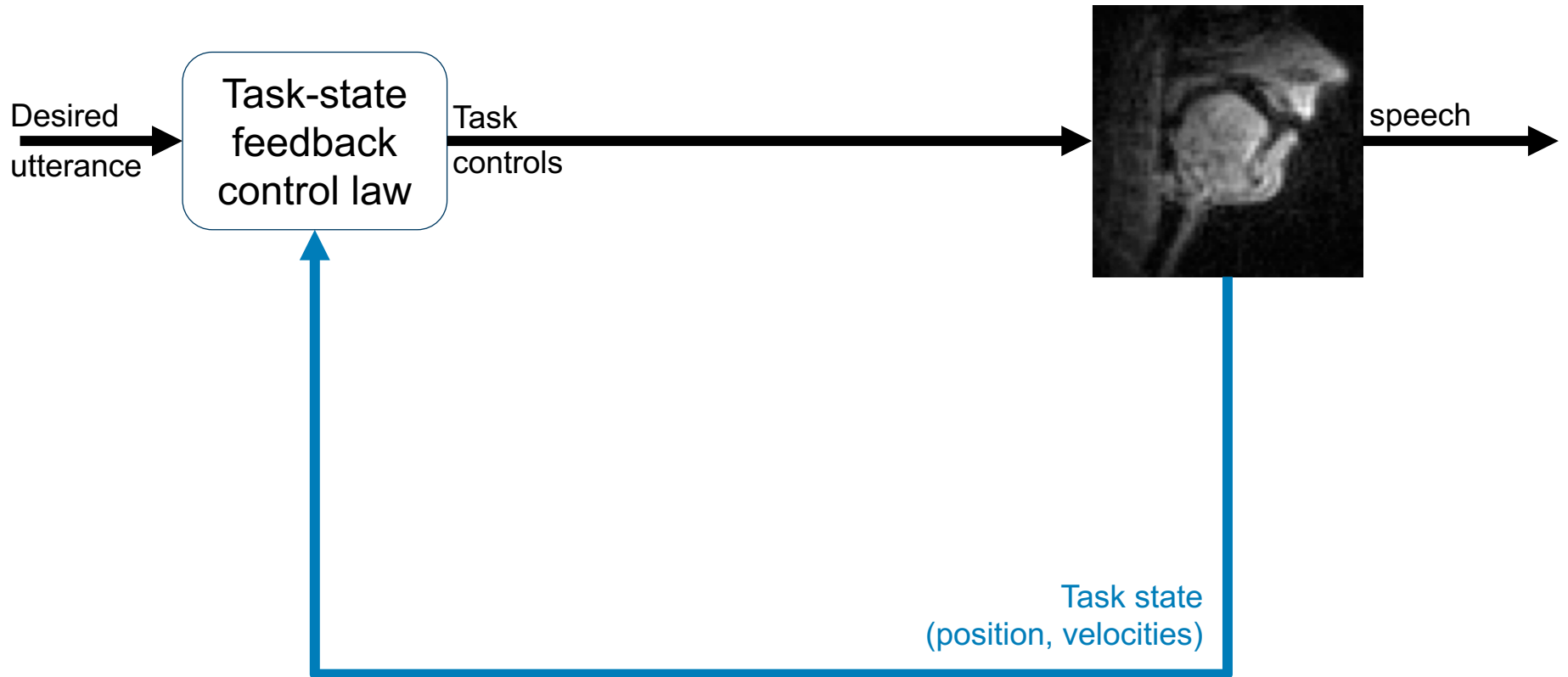
# Modeling control of speech



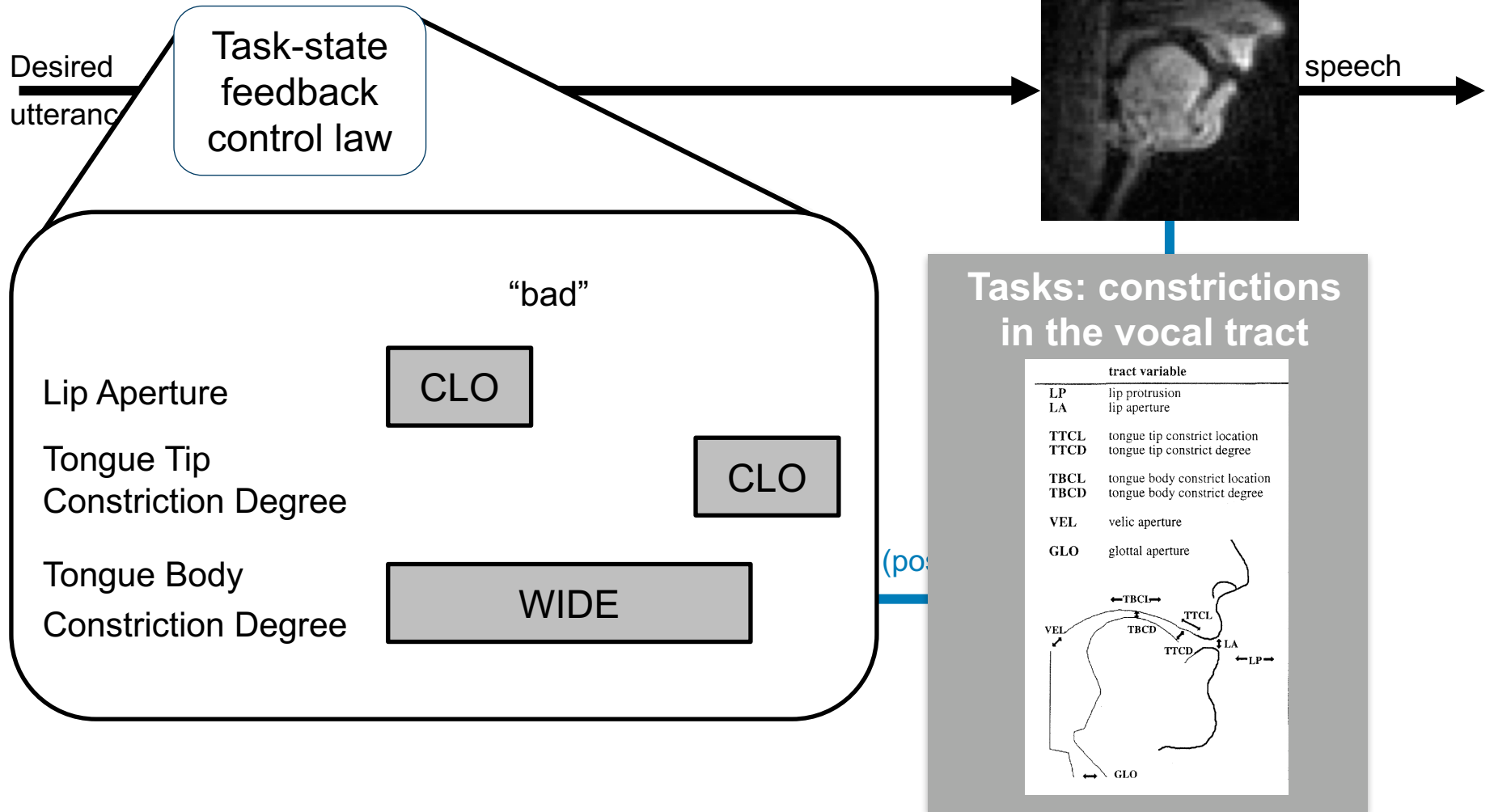
# Moving to a task-level controller



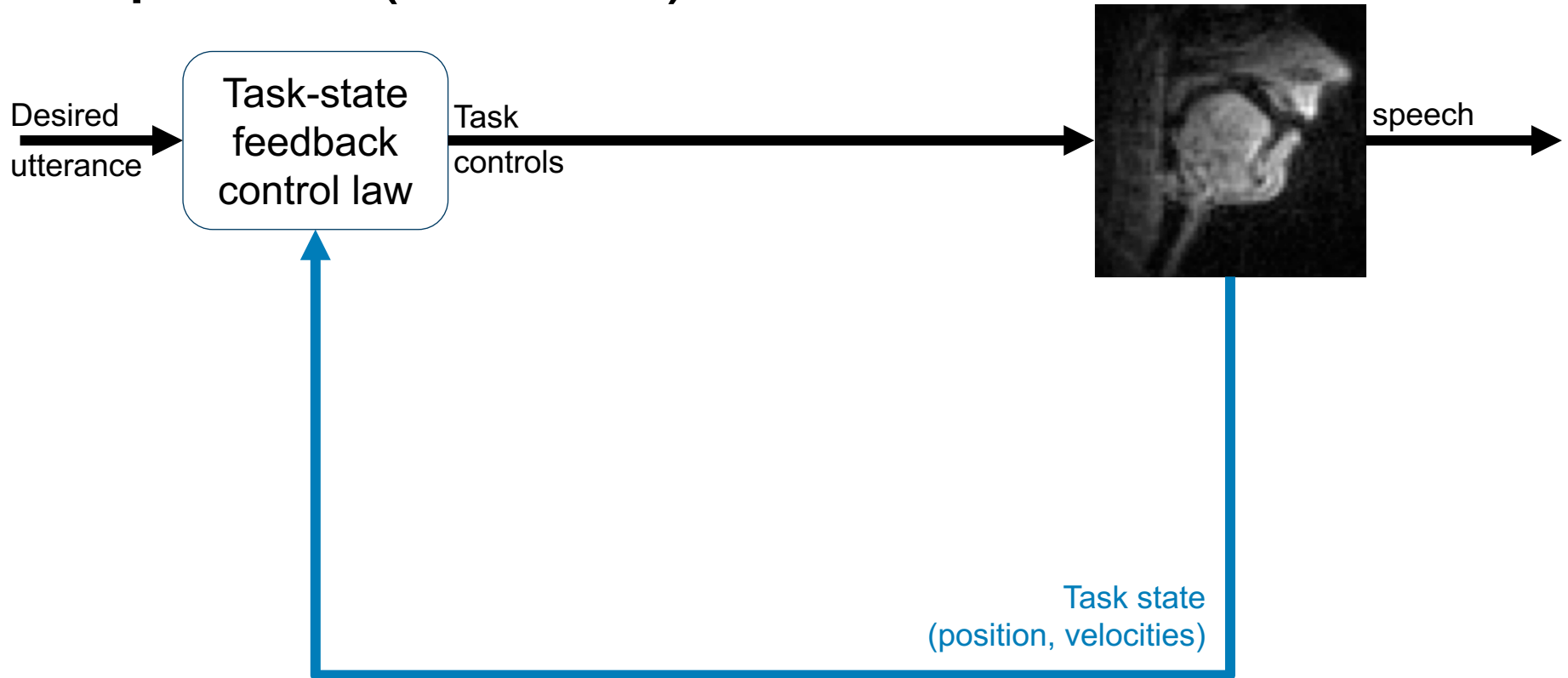
# Moving to a task-level controller



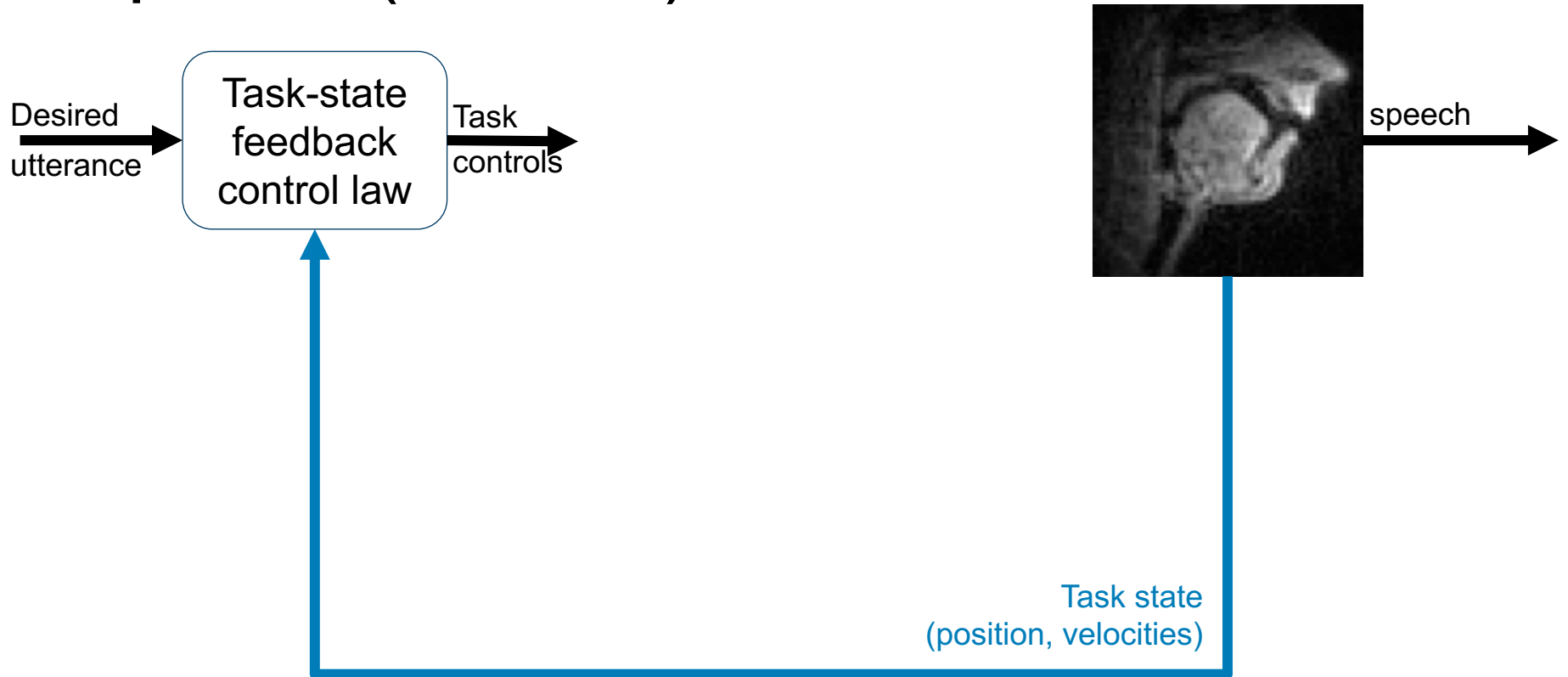
# Task Dynamics: a task-state feedback control system



# Feedback-Aware Control of Tasks in Speech (FACTS) model

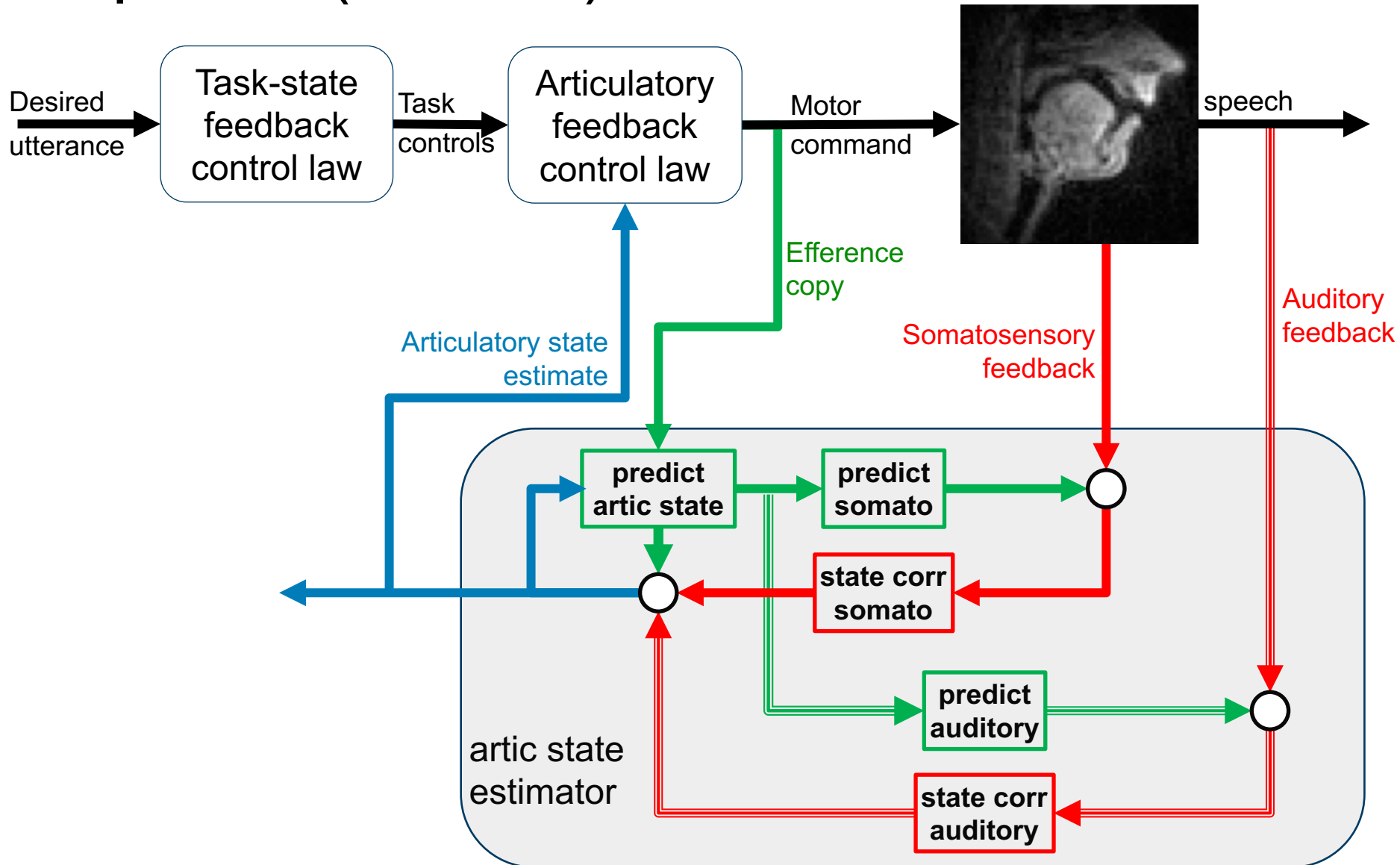


# Feedback-Aware Control of Tasks in Speech (FACTS) model

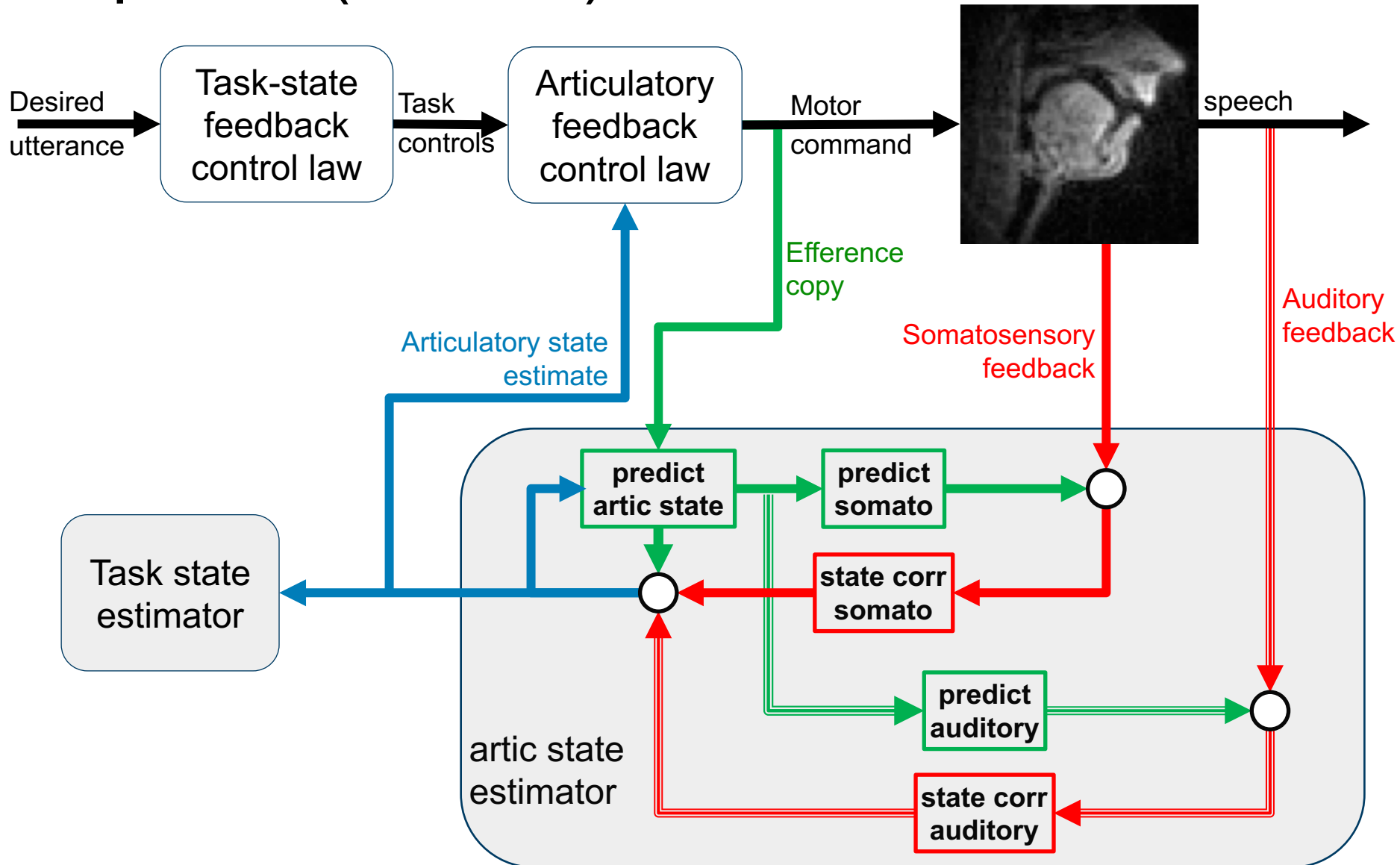




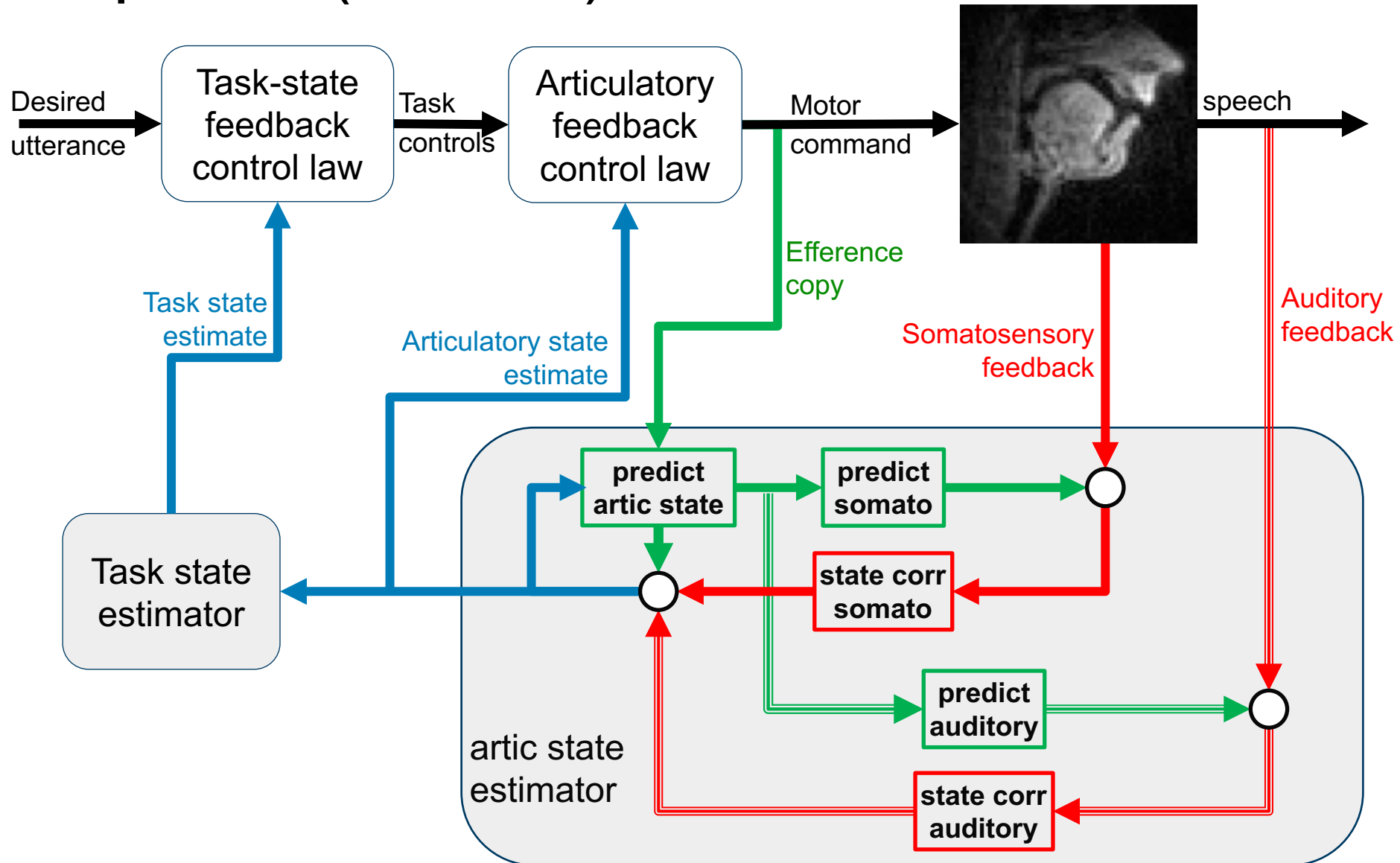
# Feedback-Aware Control of Tasks in Speech (FACTS) model



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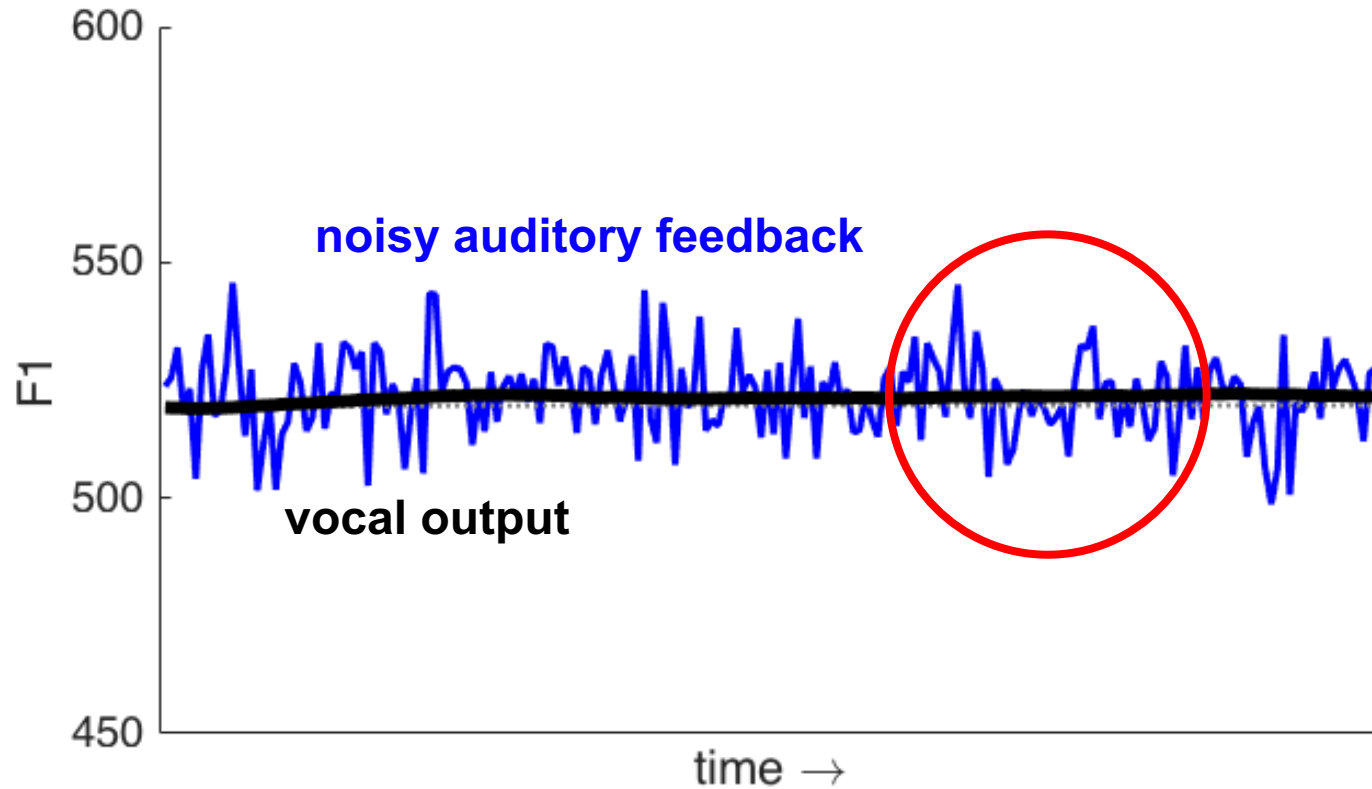


# Feedback-Aware Control of Tasks in Speech (FACTS) model



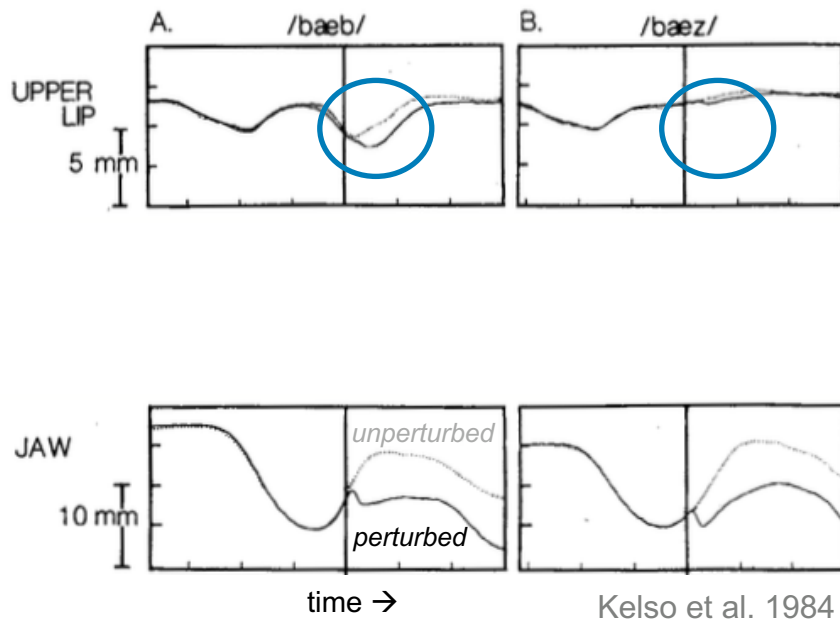
FACTS produces stable speech in the presence of sensory noise

model producing /ε/

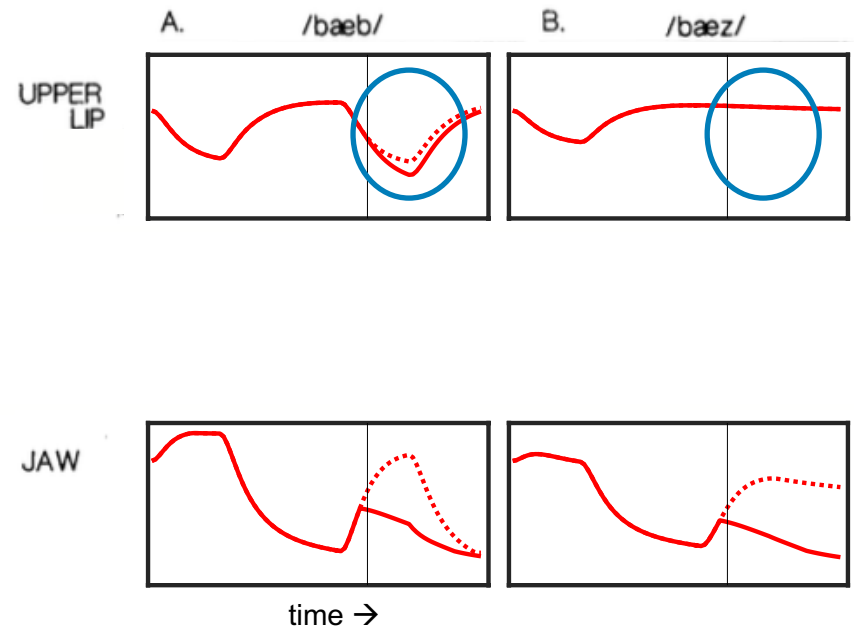


# FACTS simulates task-specific responses to mechanical perturbations

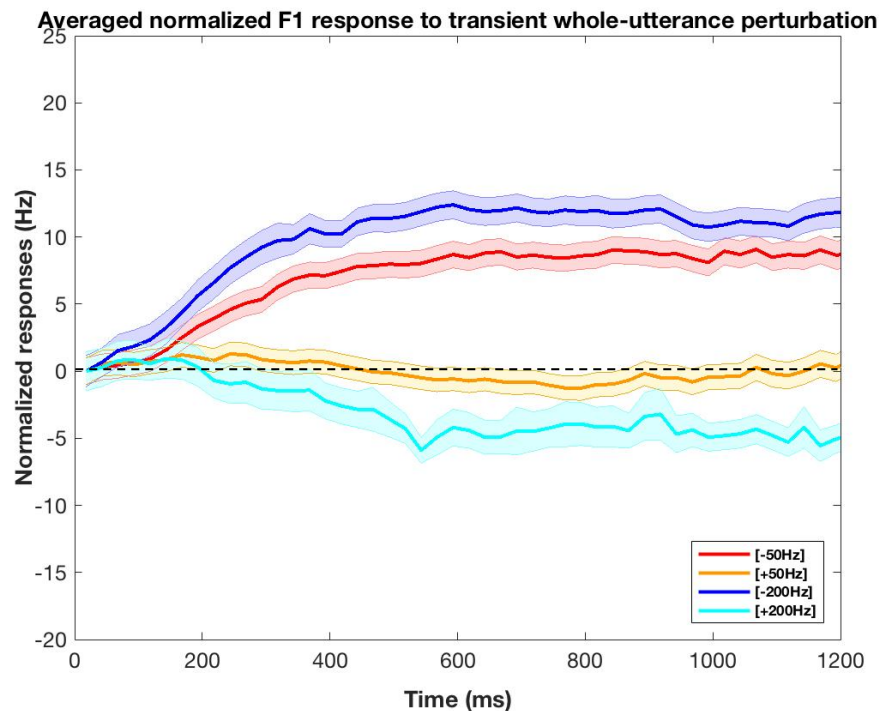
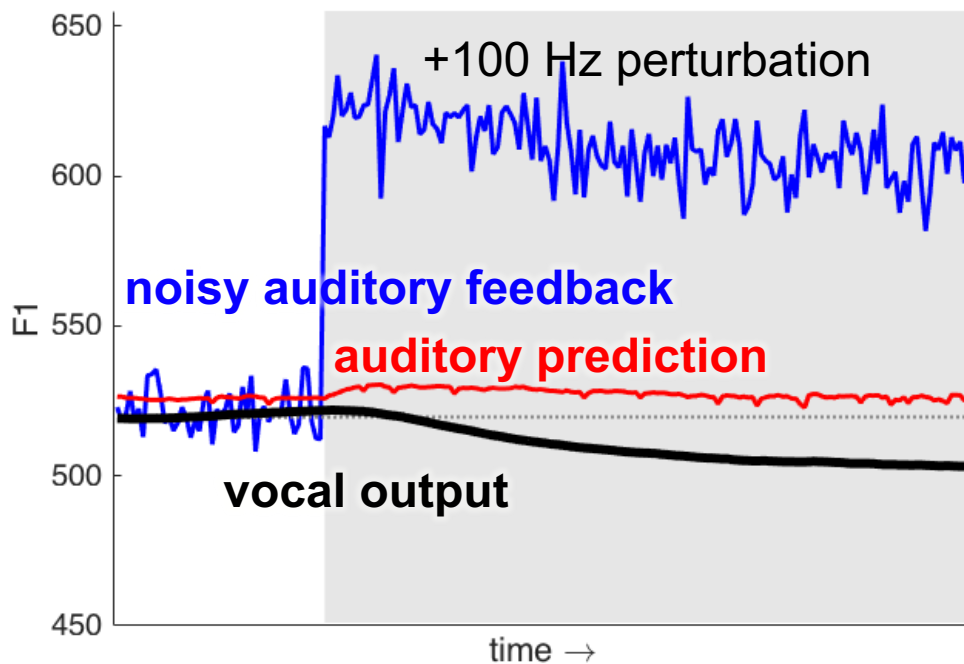
Human data



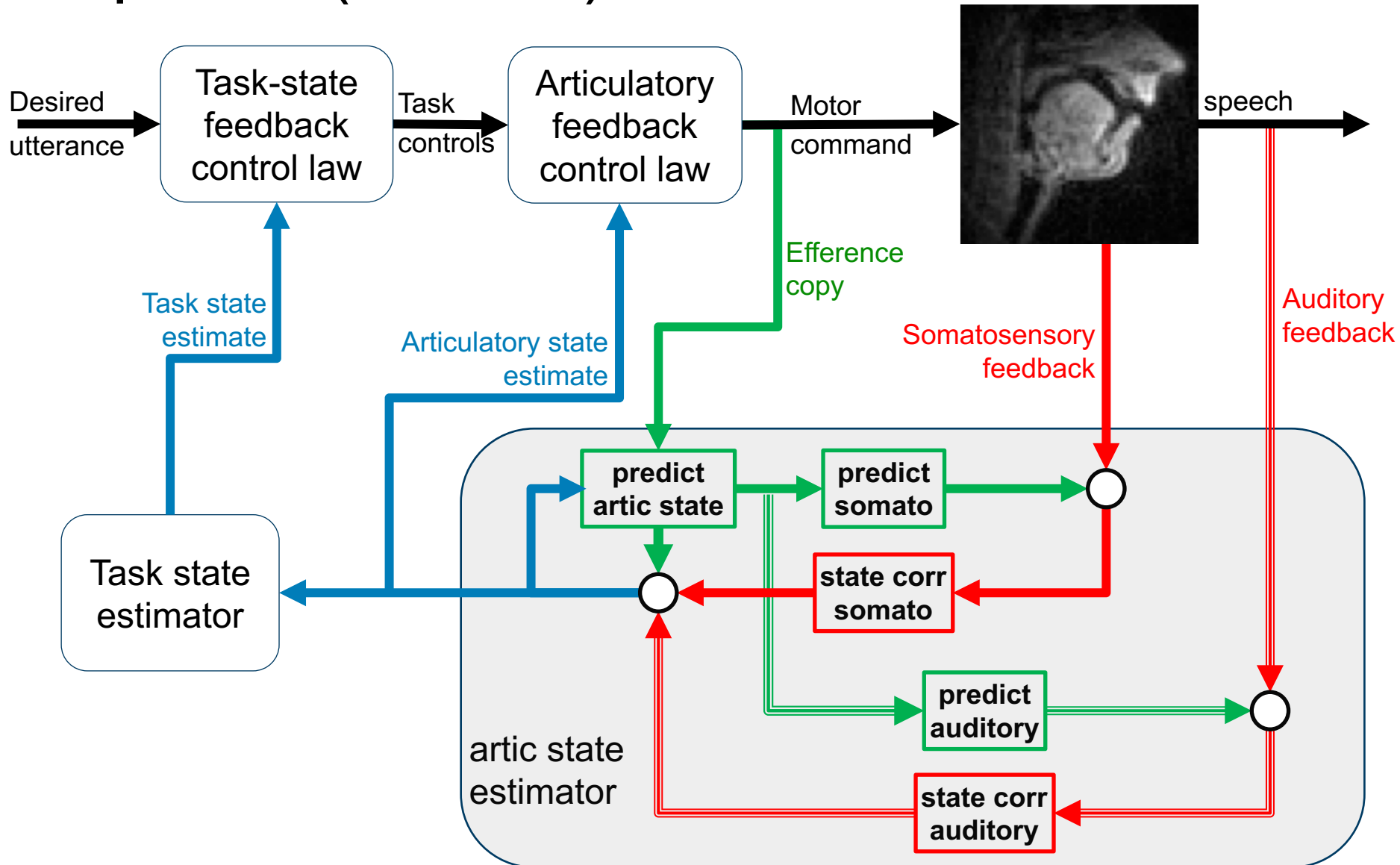
Model data



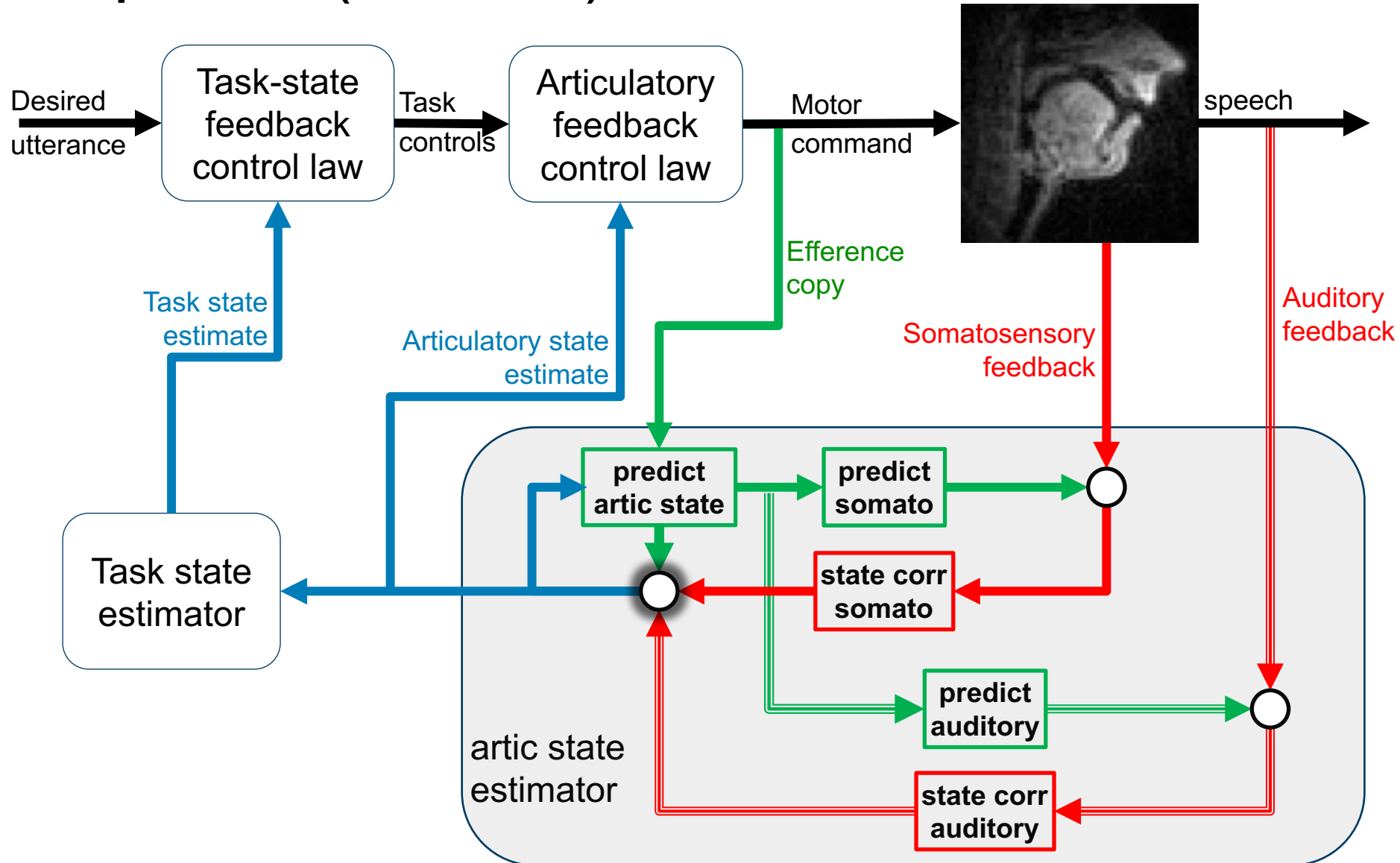
# FACTS simulates partial compensation for auditory perturbations



# Feedback-aware Control of Tasks in Speech (FACTS) model

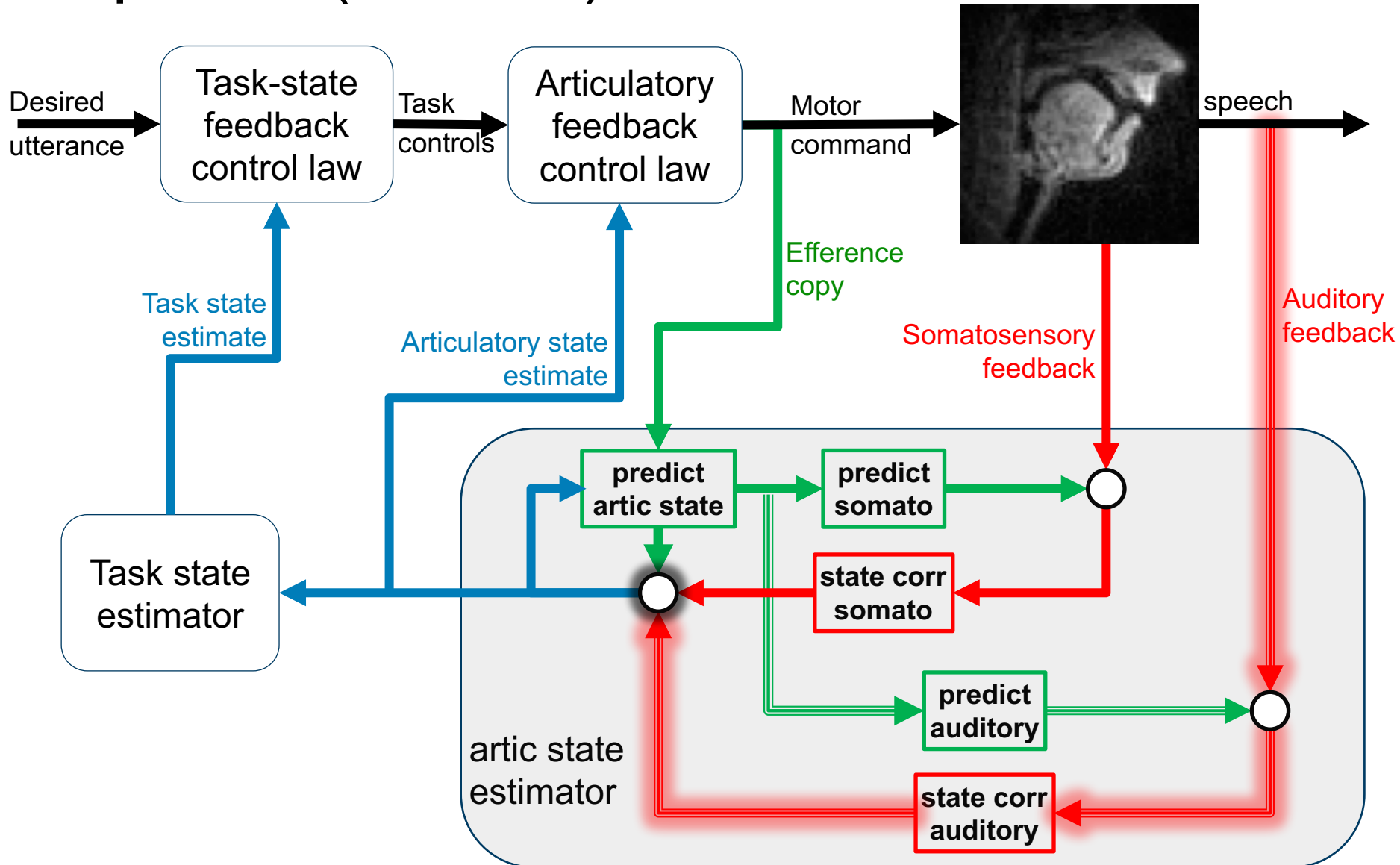


# Feedback-aware Control of Tasks in Speech (FACTS) model

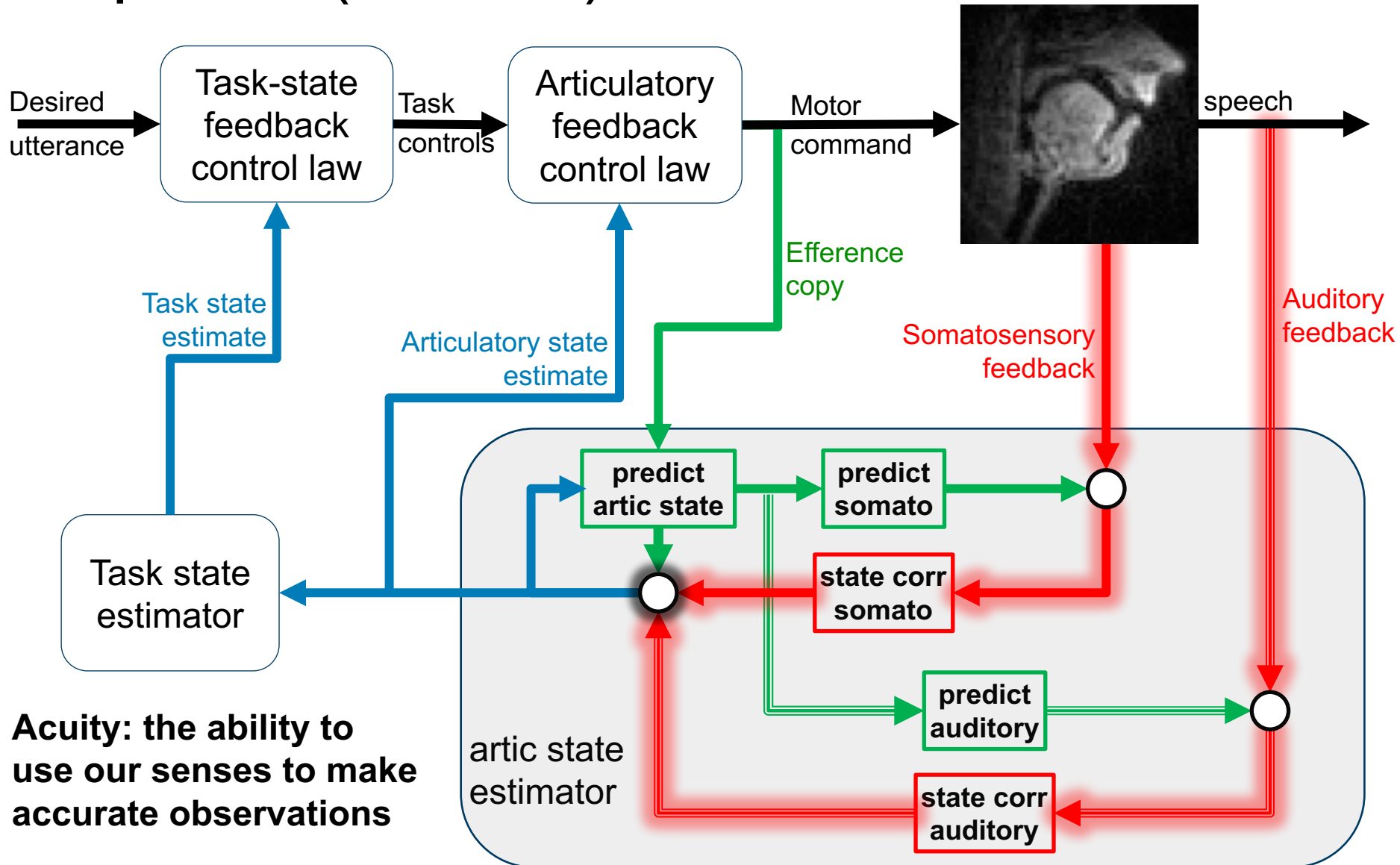




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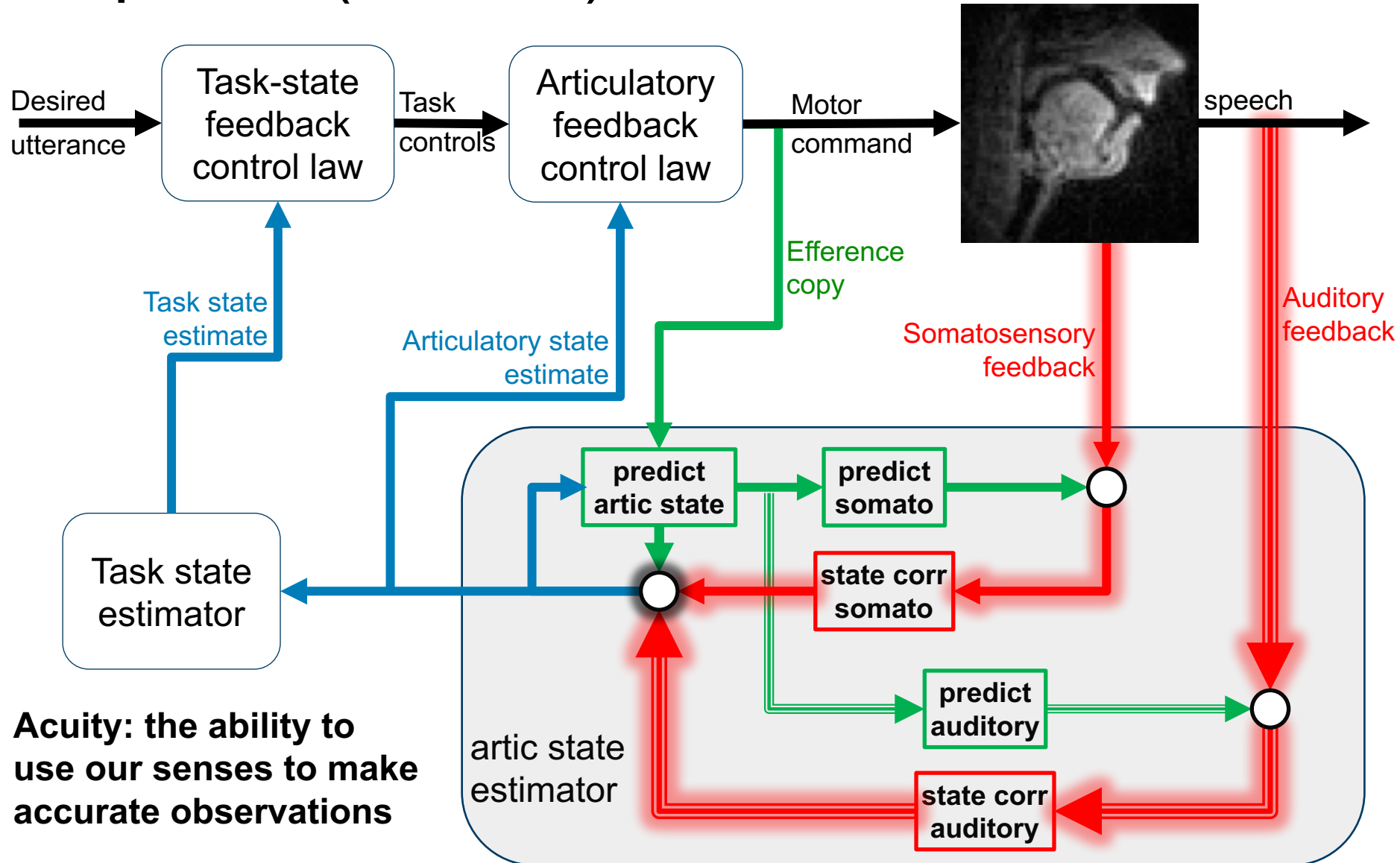


# Feedback-aware Control of Tasks in Speech (FACTS) model



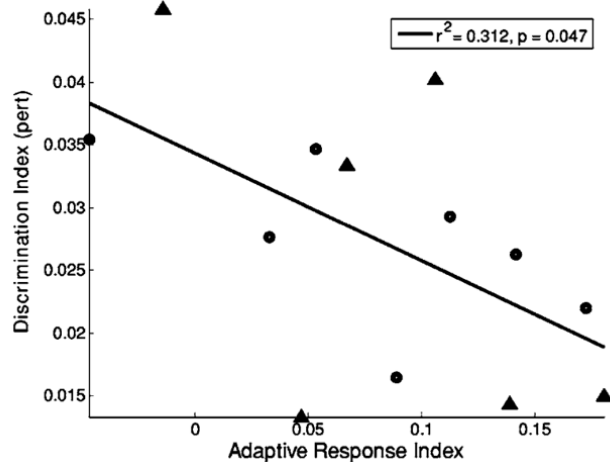
**Acuity: the ability to use our senses to make accurate observations**

# Feedback-aware Control of Tasks in Speech (FACTS) model



# Some evidence for acuity-response relationship

Speakers with better auditory acuity adapt more to auditory perturbations

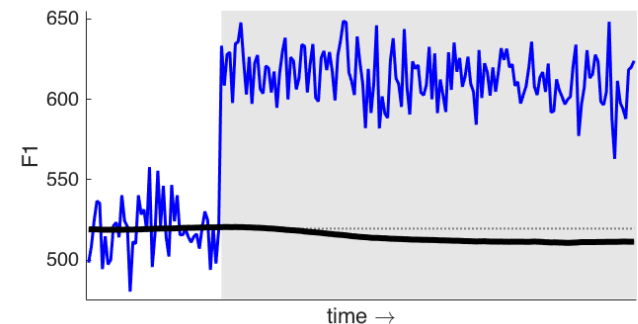
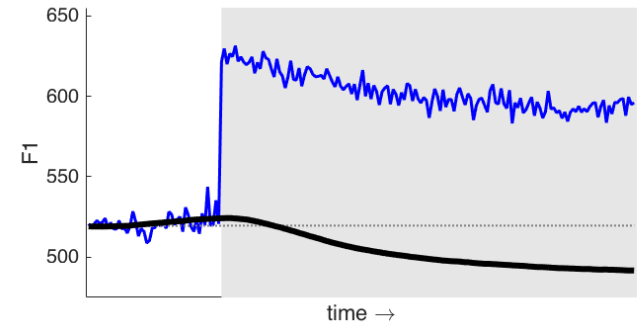
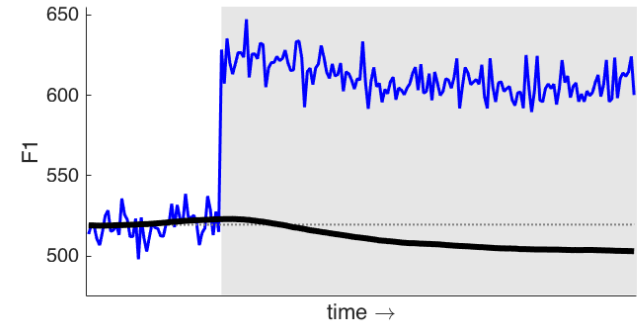


Villacorta et al. 2007

↑ auditory acuity

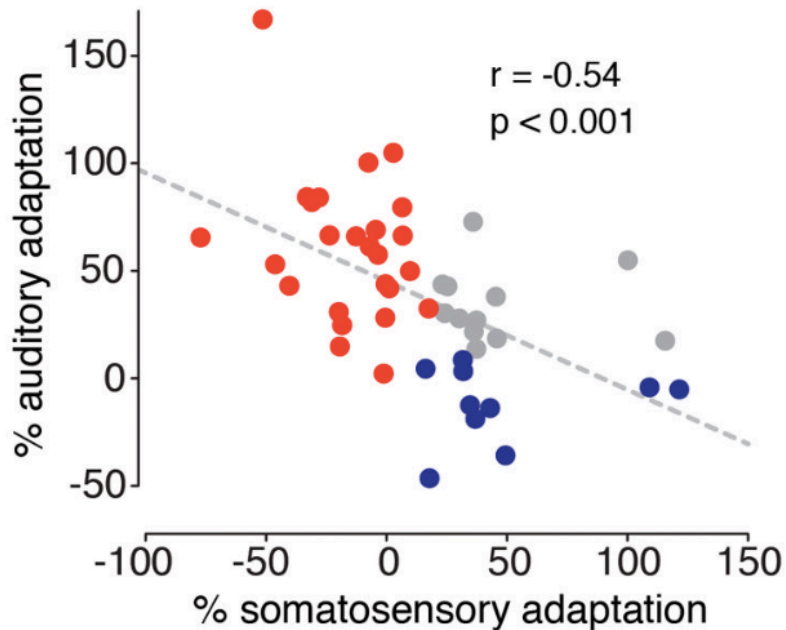
↓ auditory acuity

Baseline response



# Some evidence for acuity-response relationship

Speakers' response to auditory perturbations is *negatively* correlated with their response to somatosensory perturbations



Lametti et al. 2012

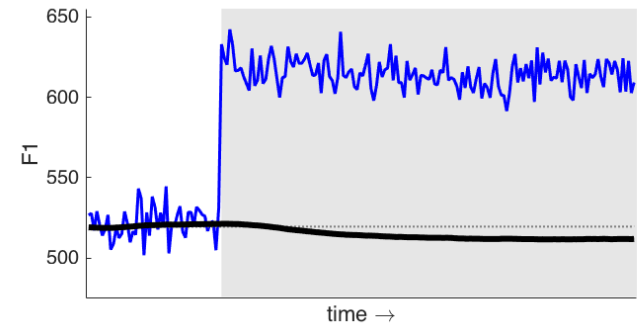
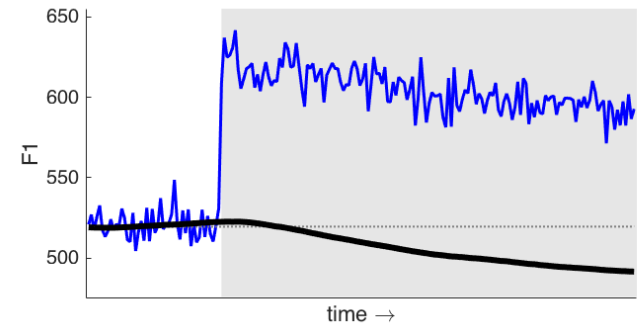
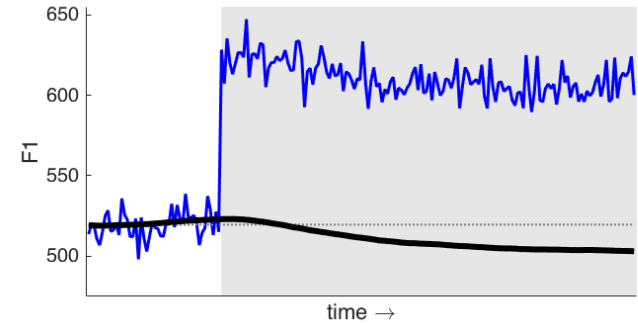
↑ **auditory acuity**

↓ **somatosensory acuity**

↓ **auditory acuity**

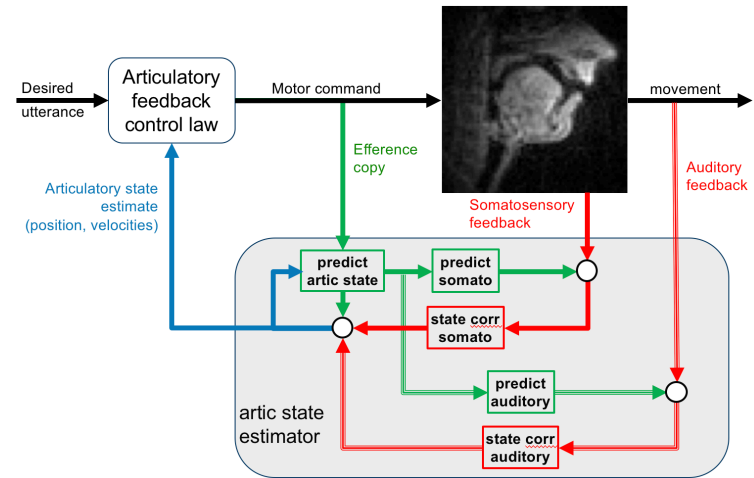
↑ **somatosensory acuity**

Baseline response



# FACTS model

- Is responsive to, but not reliant on, sensory feedback
- Produces stable speech in the presence of noise
- Reproduces full task-specific compensation for mechanical perturbations
- Reproduces partial compensation for auditory perturbations
- Models trade-off between auditory and somatosensory perturbation responses



## What's next?

- Model neural system
- How is the prediction process learned and updated?
- Is multisensory feedback combined to estimate a single state or are auditory and somatosensory signals treated separately?

# Computational implementation

